



USER MANUAL
ST2



User manual

Referred to :

Fw revision starting from 2.00
RC software revision starting from 2.00





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Description

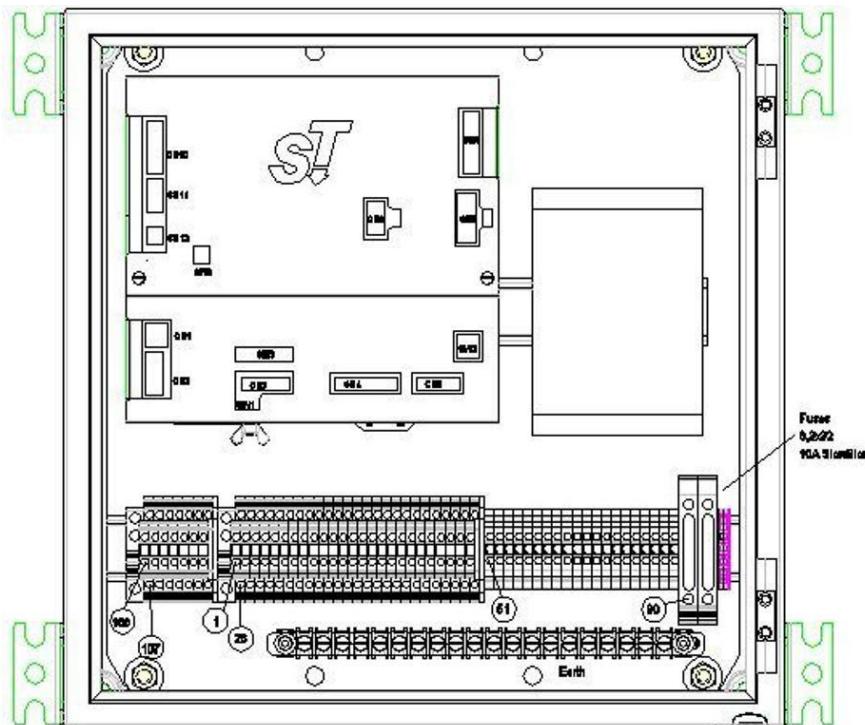
The "Smart Trak" controller is used as a positioning system for proportionally-driven hydraulic actuators. Fast stroke and superior resolution allow the unit to be applied on severe service hydraulic actuators demanding fast stroking and precise positioning. Smart Trak system covers a wide range of actuator size and stroke length requirements.

Smart Trak 2 is able to drive two fully independent actuators.

The Smart trak controller must be connected to the following devices:

1. feedback probe (for each actuator) which detects the hydraulic actuator's actual position
2. One modulating valve (for each actuator)
3. Up to 3 on-off solenoid (for each channel)
4. Optional pressure/temperature (4-20mA signal) sensors

On the customer's side power supply, 4-20mA signal (request position) and if required trip signal and output signal must be connected.



CONTROLLER MOUNTING

The controller enclosure is rated for NEMA4 (NEMA4X when the Stainless Steel) / IP66 environment, which is watertight to "wash down", such as a water hose. Outdoor mounting is acceptable, however, the controller should be protected from direct sunlight by a suitable sun shield (see temperature ratings).



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Manufacturer's identification :

Every controller Smart Trak is provided with a name plate with its serial number. The year of manufacturing is indicated by the first two numbers of the serial number.

Do not remove it and/or replace with other name plates

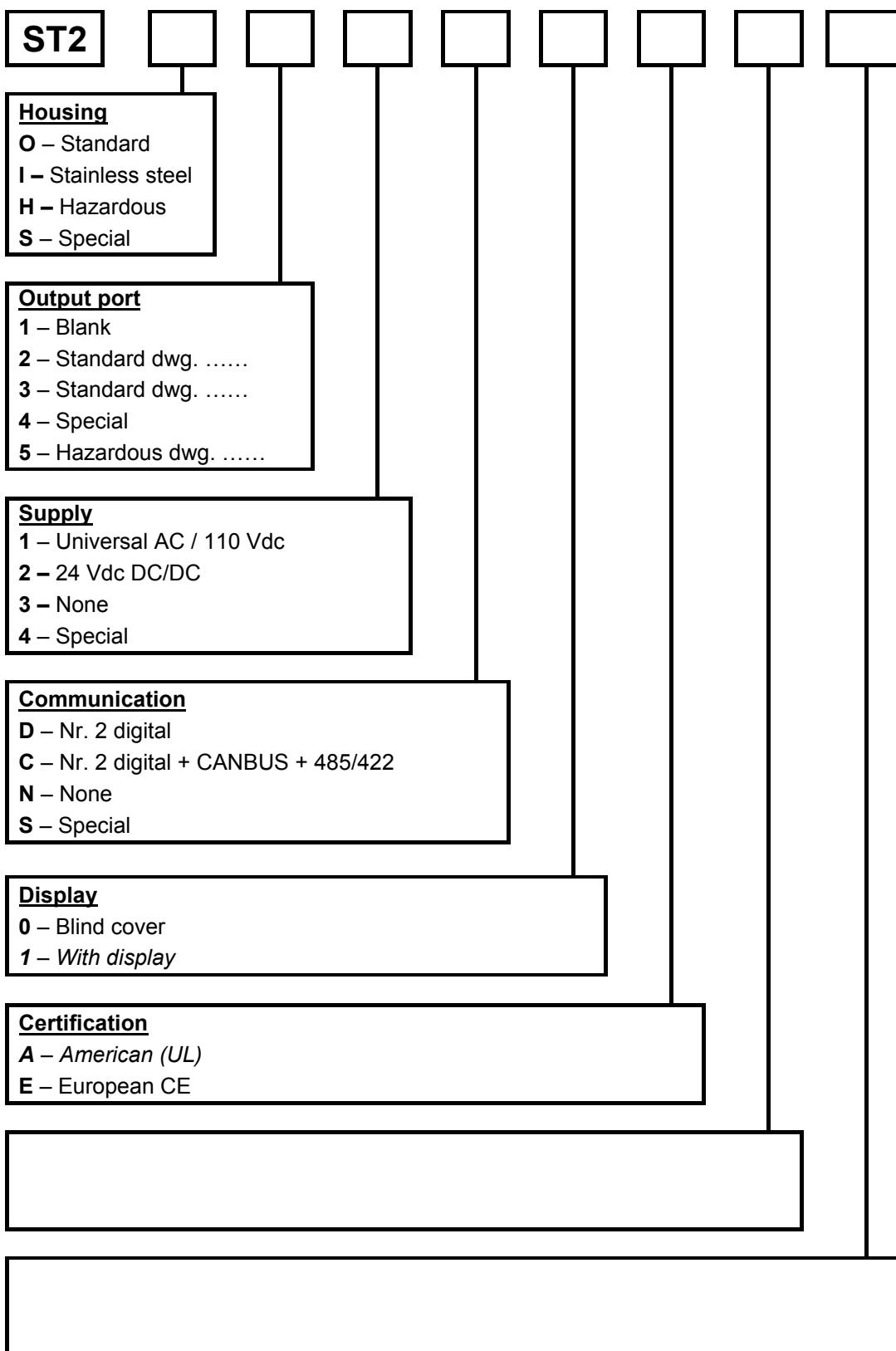


The decoder of the manufacturer's model can be made by means of the following table :



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GENERAL SAFETY INSTRUCTIONS

The non-observation of the following safety instructions and of the instruction manuals can result in serious injury.

Installation

- Must be done by qualified person trained to operate
- A ground tap is necessary
- The electrical and hydraulic connections must be done according to the diagram and label
- The supply circuit must be protected in case of current exceeding the limit fixed
- The equipment must be provided with cable entries and filler plugs certified according to the required certification
- The actuator must be installed and used according to the project design specification.
- The fluid must be chemically compatible with the used gaskets and lubricant

Maintenance

- Must be done by qualified person
- Cleaning must be done with a humid cloth
- Greases and oils must be used according to the manufacturer's instructions, however their flammability point must be $> 140^{\circ}\text{C}$



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Controller sw upgrade

The software is factory installed in the controller. For a new installation, a "Loader" program is necessary. It can be installed selecting the file SETUP.exe from the supplied LOADER software cd.

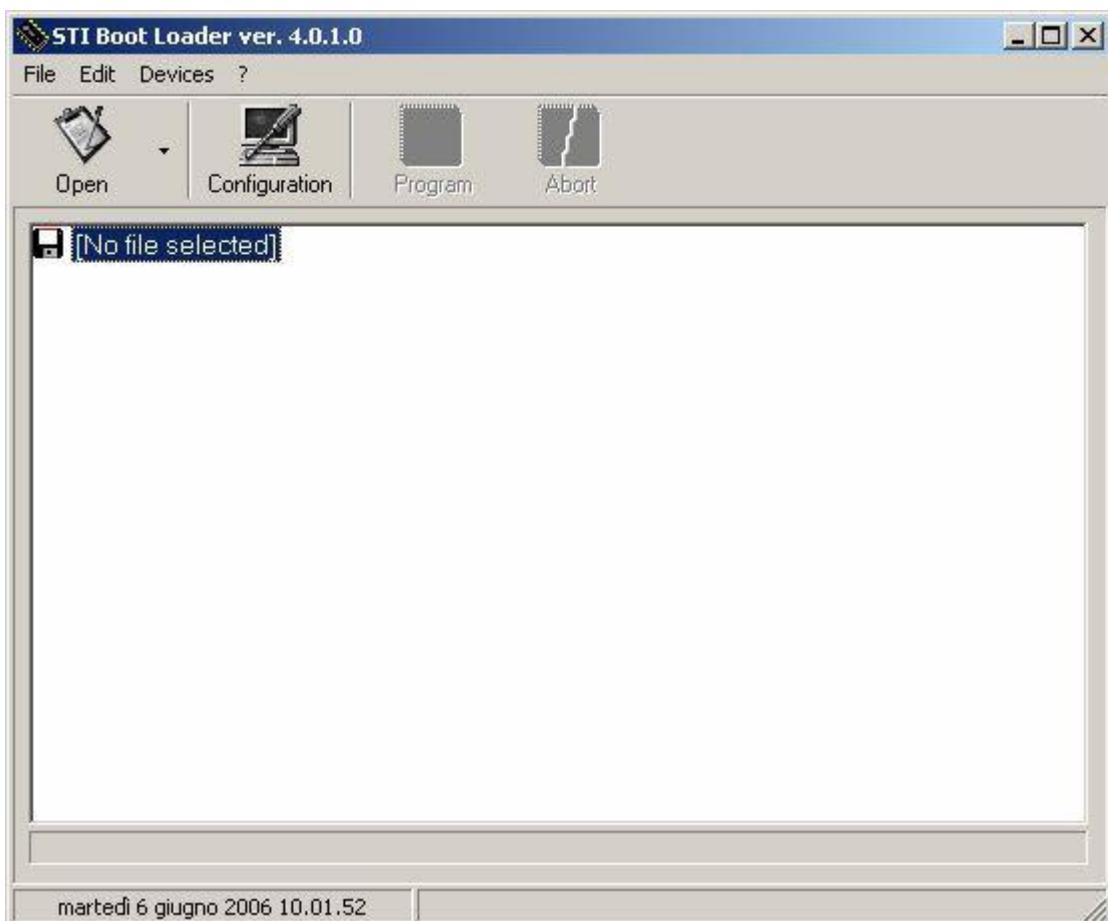
A shortcut should appear in the program selection of start menu. Select the "Loader" access program:

Program » Loader » Loader

Or select it directly:

C:\Program Files\STI s.r.l\Loader\Loader.exe

The following window will appear:





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Configure the PC COM port selecting: "Configuration" from EDIT menu for "Texas 2812 DSP".



Copy the DSP software to be installed to a folder on the laptop. File extension should be ".hex".

Perform the following steps on the Smart Trak controller to prepare it for software loading.

- Turn off the controller by the main power switch
- Change the switches SW1 as showed in SW Upgrade mode

NORMAL



SW UPGRADE mode



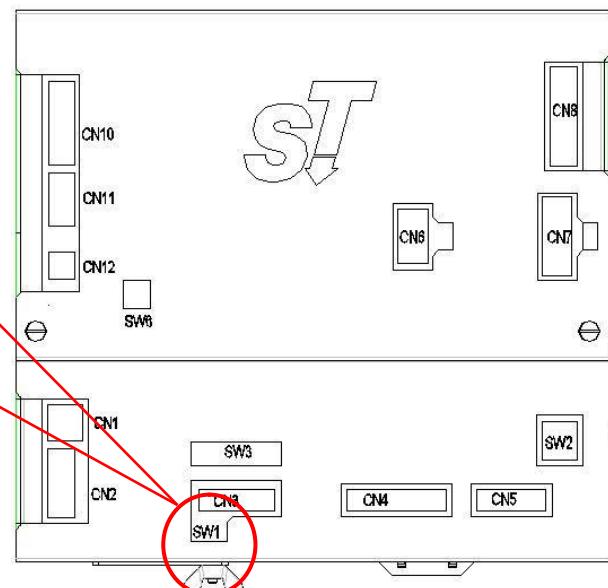
Attach the USB cable to the CN1 connection block

- Launch the loader program
- Select the down arrow next to the "OPEN" quick select button
- Select "Texas 2812 DSP File"
- Locate the .HEX file, and select OPEN
- Turn on the controller
- Select the "Program" quick select button
-



The program should run to completion

- Upon completion select File » Exit
- Turn off the controller
- Change the switches SW1 as showed in Normal mode.





RemoteControl sw installation

- Insert the CD (or download the installation file)
- Run setup.exe
- Follow the instruction on the desktop

RemoteControl sw connection

USB connection :

Connect a standard USB 'A' to 'B' cable from your computer to the ST2 USB port CN1



When the USB connection is used a specific USB driver is required.

The USB driver is usually provided with the RemoteControl installation file or can be download from <http://www.ftdichip.com/Drivers/VCP.htm> with reference to FT232R device.

If communication problems are recognized check the 'latency timer' in the advanced properties of the COM port assigned and set it to 1ms.

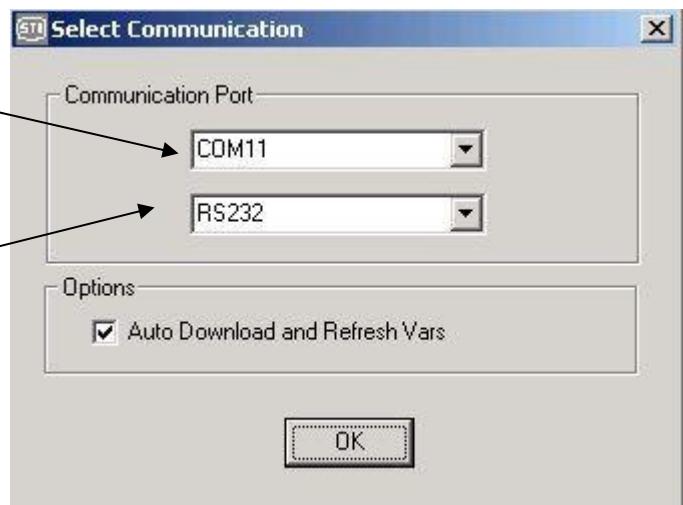


Starting the sw

- Run the sw starting from the desktop icon or from the Windows Start menu.

The 'Select Communication' page is displayed.

- Select the right communication port
 - Only the available communication ports are displayed in the combo box.
- Select the Communication mode (RS232 or HART)
- Press the 'OK' button





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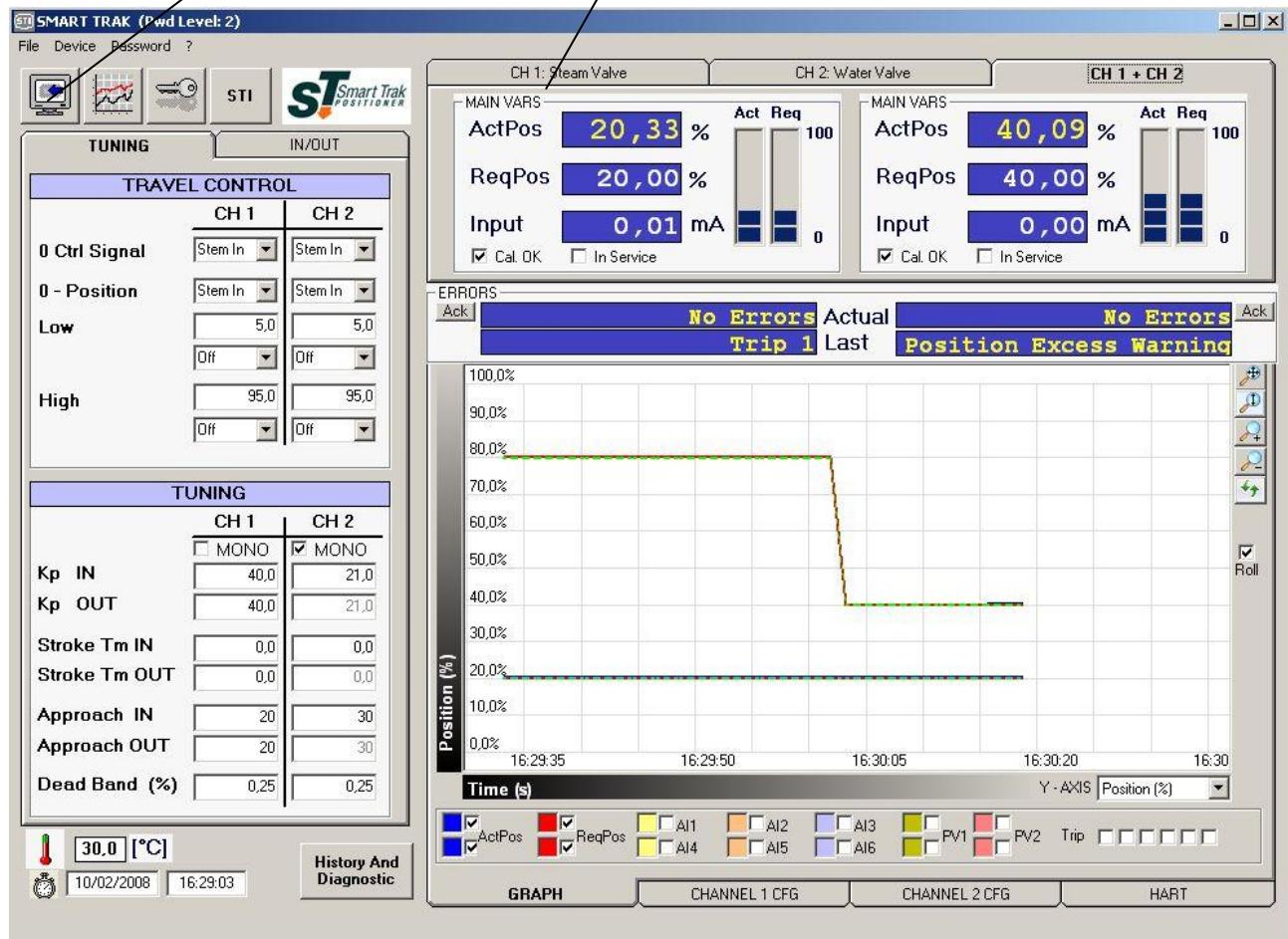
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The Main page

QUICK
BUTTONS

MAIN VARS





Quick Buttons

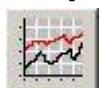
Download button



Download all the parameters from ST2.

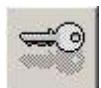
At the end of the download the values displayed on the RC sw are the same of the ST2 positioner

Graph button



Open the Graph window

Password button



Open the Login window

In order to change the parameters value or to access the various configuration windows a login is request.
The default standard password is : 12345

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‘Tuning window’

‘Travel Control’ area

Definitions :

Limit : when a limit is configured the Request position is limited at this value

Example : Set the Limit at 95%. Even if the signal input is 20mA and the theoretical Request position is 100%, the applied Request position is 95%

CutOff : When a cutoff is configured if the Actual position falls inside the Cutoff area the Request position is fixed at the min (or max) value.

Example : Set the cutoff at 5%. When the Request position is less of 5% and the Actual position is less of 5% a fixed pressure is applied in order to put the actual position at 0%.

WARNING

On some type of valves it is mandatory to enable a cutoff to ensure that the valve works properly (to ensure full trust on sit)

0 Ctrl Signal :

Specify the relationship between 4-20mA signal input and stem position.

‘Stem in’ means that you want that the Stem is in ‘in position’ when you apply 4mA

‘Stem out’ means that you want that the Stem is in ‘out position’ when you apply 4mA

0 Position :

Specify the relationship between 0-100% indication (a 4-20mA Out) and stem position.

‘Stem in’ means that 0% position is when the Stem is in ‘in position’

‘Stem out’ means that 0% position is when the Stem is in ‘out position’

Low [0..50 %]:

Specify if a Limit or a CutOff is configurated in the close direction.

High [50..100 %]:

Specify if a Limit or a CutOff is configurated in the open direction.

Tuning :



A lot of parameter are configurable with a different value in the Open direction and in the close one. This is to maximize the performance of the system.

If the *Mono* flag is checked the first value of each parameter is automatically copied in the second one.



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Kp IN/OUT [0 .. 100]:

Proportional gain is the multiplier of the error (difference between input signal and actuator actual position) and it is expressed in percent. It is active only for an error which is bigger than dead band value.

A different gain for each stem direction can be imposed.

Stroke Time IN/OUT [0,0 ..3000,0 sec]:

The value expressed in seconds of the stroking time for each direction

Approach IN/OUT [0..100]:

Special parameter, similar to a derivative factor, used to control overshoot.

Dead Band [0..10] :

Dead band prevents (at expense of the accuracy) that the valve, in the controlled condition, keeps continuously hunting for the target position



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'IN/OUT window'

Fail/Trip settings

Configure the digital input for TRIP function.

Up to 6 digital input are available.

For each digital input you can configure :

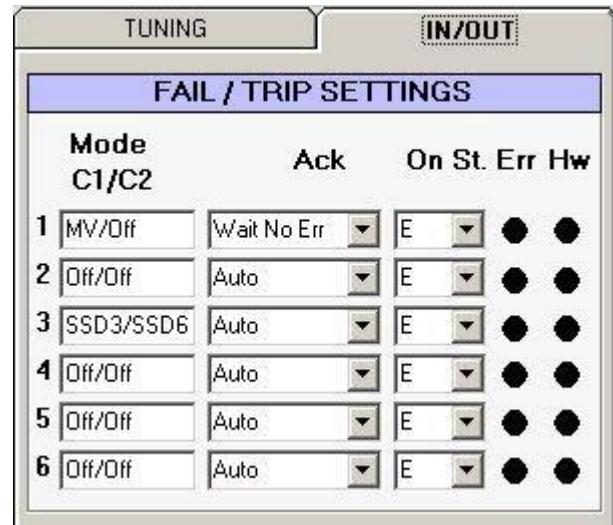
Mode C1/C2 :

Error mode for channel 1 and channel 2.

It is possible to define the action to do when the TRIP input is ON.

Normally a TRIP is related only to one channel, but it is possible to set an error mode for both the channels.

- *Off/DirectDriveMode/Booster Enabled Mode :*
The TRIP is not used or it is assigned for Direct Drive function (See SOV configuration)
- *SafetyShutdown :*
Up to 3 different Safety mode for each channel.
The SOV activation in each SafetyShutdown mode is define in the SOV configuration panel
- *Modulation valve :*
The actuator is driven to a specific position specified in the 'Pos' field that is showed when 'Modulation Valve' is selected
- *Freeze :*
Actuator freezes in the last position
- *Ack :*
Trip is used for the error acknowledgment in remote mode.
- *External SOV :*
External safety shut down valve has been activated.



Ack END MODE

The end mode option allows to configure the action to be executed at the end of the error conditions.

On St.

This option allows to configure the ON status for the selected trip.

'E' means : when the input is energized (contact is closed or voltage is applied)

'nE' means : when the input is de-energized (contact is open or voltage is not applied)

For safety reason the best choice is 'nE' : if a wire is cut off you are able to recognize this potential problem

Err : Led used to show if a trip is activated (trip status , energized or not, is equal to 'On St' and a function , Mode C1/C2) is defined.

Hw : Led used to show if a trip is energized or not

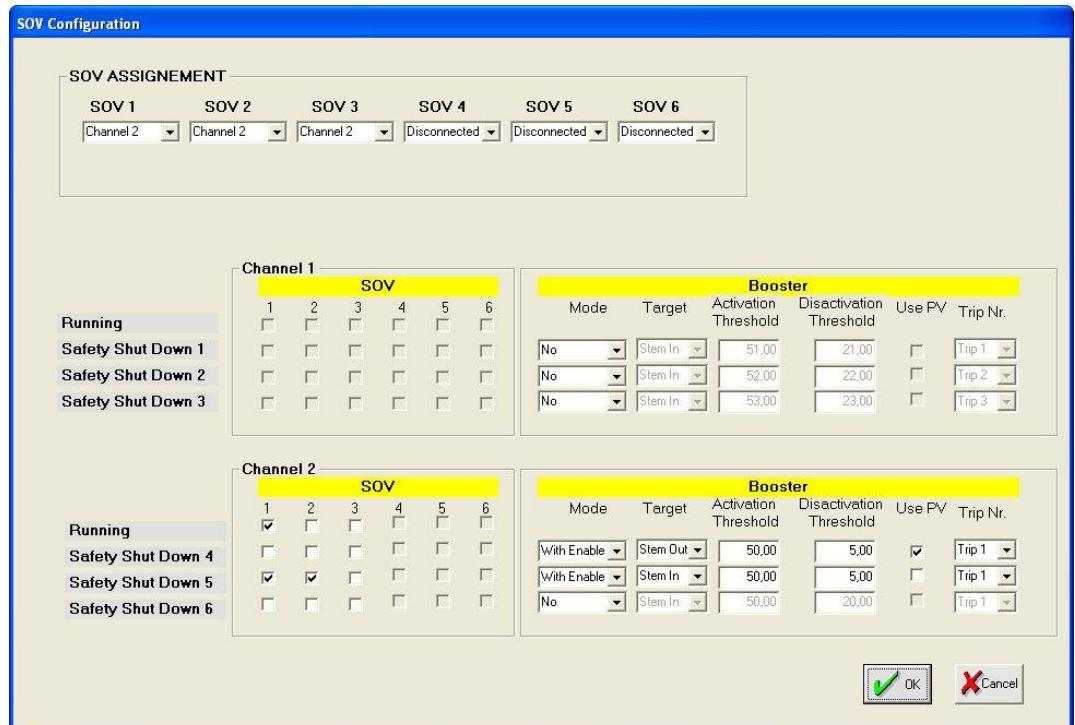
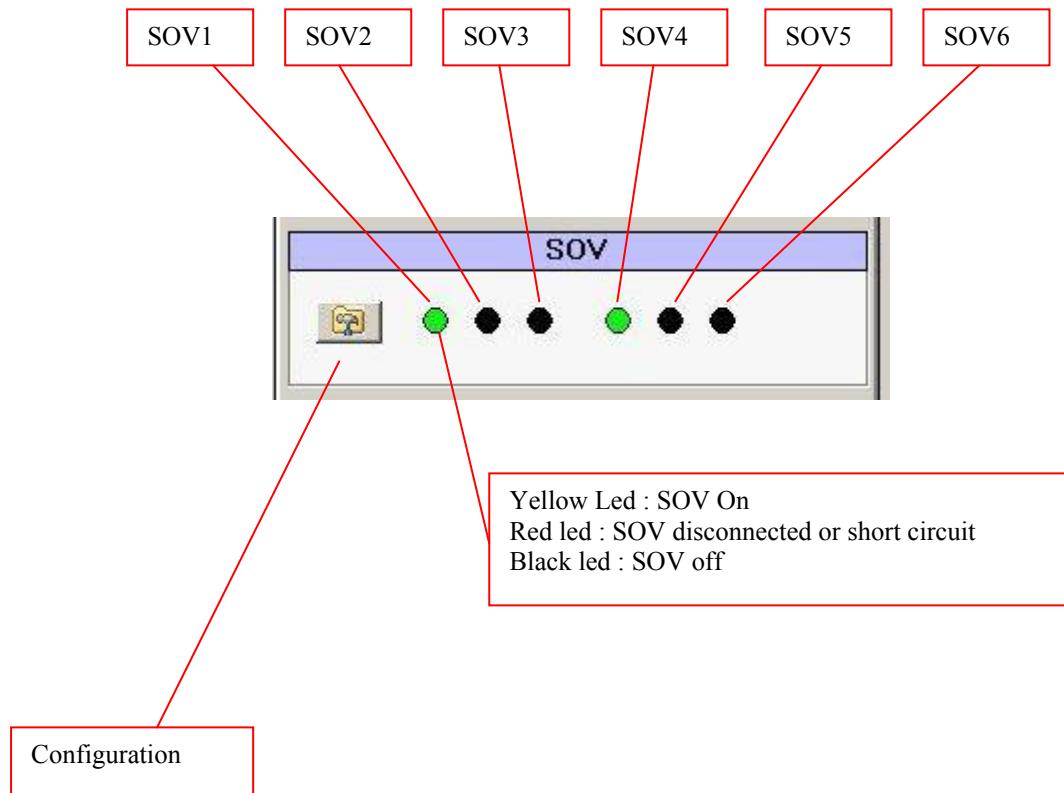


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SOV





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SOV ASSIGNEMENT

Select if a SOV is assigned to Channel 1 or Channel 2 or if it is reserved for DirectDrive.

Selecting DirectDrive a SOV is not assigned to a specific channel and can be activated from a trip. This mode is used typically to drive ON/OFF Valve without feedback.

When a specific trip is assigned to a SOV for direct drive, a warning is showed if the trip is already assigned for other functions.

Channel 1 :

Only the SOV assigned to channel 1 are active and configurable in this panel.

The matrix specify if a SOV is activated or not in a specific Running/SafetyShutdown status.

Refer to “Configure SOV and TRIP” at the end of this instruction manual to understand how to set the SOV.

Channel 2 :

Only the SOV assigned to channel 2 are active and configurable in this panel.

The matrix specify if a SOV is activated or not in a specific Running/SafetyShutdown status.

Refer to “Configure SOV and TRIP” at the end of this instruction manual to understand how to set the SOV.



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SOV BOOSTER FUNCTION

This feature come with sw release 2.0 .

The ON/OFF valves can be used in order to speedup the movement of big actuators.

Two operative modes are available :

- With enable
- Normal

When Booster 'with enable' is selected a specific TRIP signal is used like ENABLE of the booster : it means that you can have a big error and that the movement can happens only with the proportional valve (if the TRIP is not activated) or also with the ON/OFF valve.

When Booster 'normal' is selected every time the error is greater than the activation threshold the ON/OFF valve is used.

The Booster function is related to a SafetyShutdown mode and not to a specific SOV because in order to move in one specific direction the status of more than one SOV must be changed.

Configuration parameters :

SOV					
1	2	3	4	5	6
<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

Mode	Target	Activation Threshold	Disactivation Threshold	Use PV	Trip Nr
With Enable	Stem Out	50.00	5.00	<input checked="" type="checkbox"/>	Trip 1
With Enable	Stem In	50.00	5.00	<input type="checkbox"/>	Trip 1
No	Stem In	50.00	20.00	<input type="checkbox"/>	Trip 1

OK Cancel

Mode :

No : booster function is disabled

Normal : booster function is enabled all the time based on the other configuration parameters

With Enable : booster function is enabled based on the status of the TRIP channel specified on the same row

Target :

We need to specify if this 'safety shutdown' mode move the actuator in the 'Stem IN' or 'Stem OUT' direction. Make attention : a wrong settings can cause an hydraulic short circuit (if the proportional valve is used with the booster)

Activation Threshold :

Is the minimum error that can start the booster activation

Disactivation Threshold :

Is the residual error (when we are approaching the target) that stop the booster activation

Use PV :

If this caption is selected the proportional valve works helping the movement during the booster action

Trip Nr :

This parameter is used only when the mode is 'With enable' and specify the TRIP channel used to enable the booster function.



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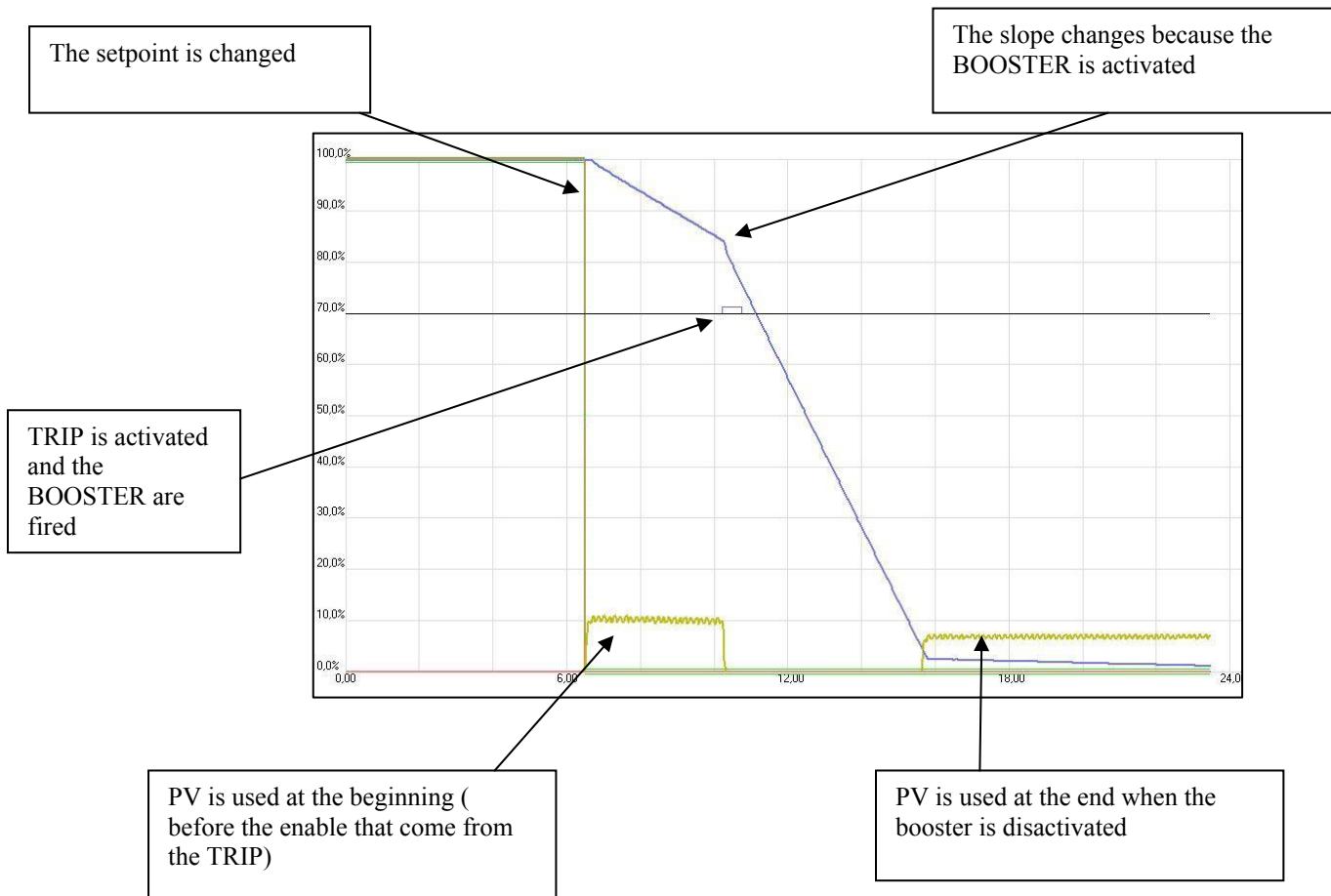


The TRIP signal is evaluated 'on the edge' and not 'on the level', it means that in order to enable the booster the TRIP status must change from 'not active' to 'active'. It cannot be 'active' all the time, if you need the booster all the time you need to select mode='Normal'

When the Mode is 'With Enable' the SafetyShutdown mode related to a booster cannot be used like in the previous sw versions for a Quickopen or QuickClose function because it is automatically deactivated when the error is less than the 'deactivation threshold'.

Examples of movement :

Booster 'with enable', PV not used.





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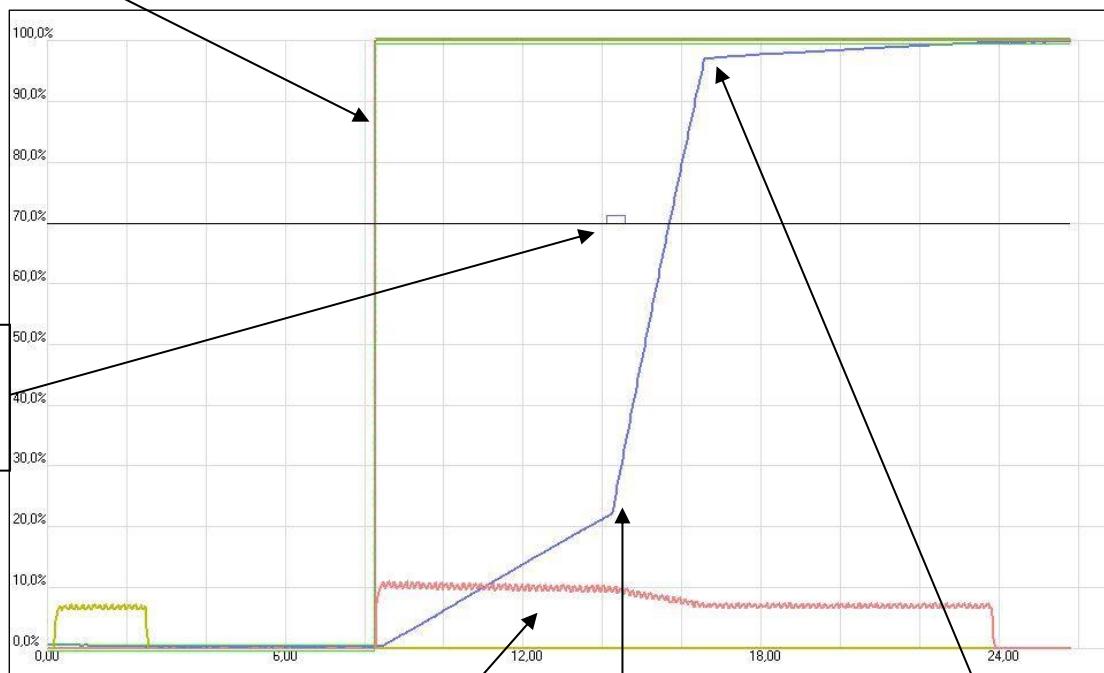
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Booster 'with enable', PV used.

The setpoint is changed

TRIP is activated
and the
BOOSTER are
fired



PV is used all the time

The slope changes because the
BOOSTER is activated

The slope changes again because
the BOOSTER is deactivated

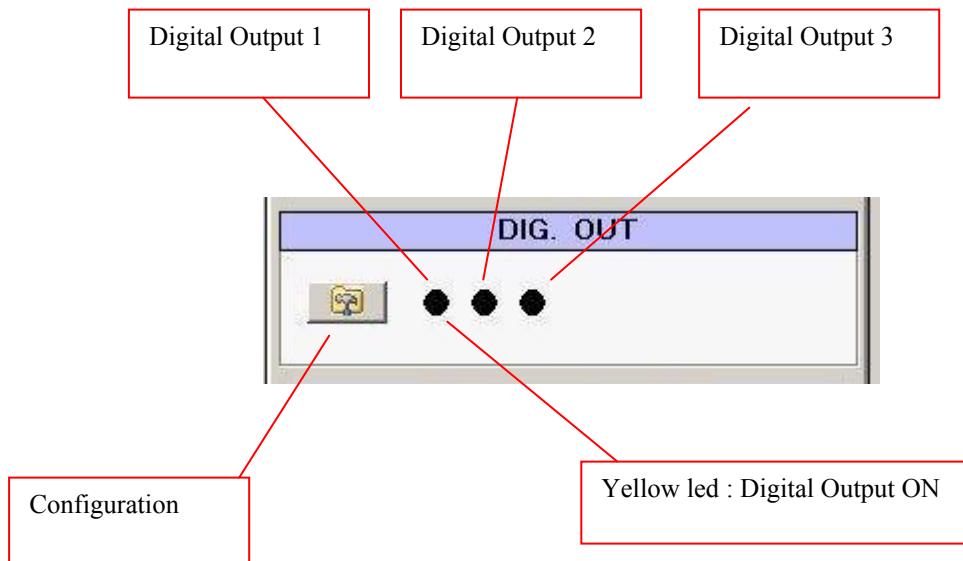


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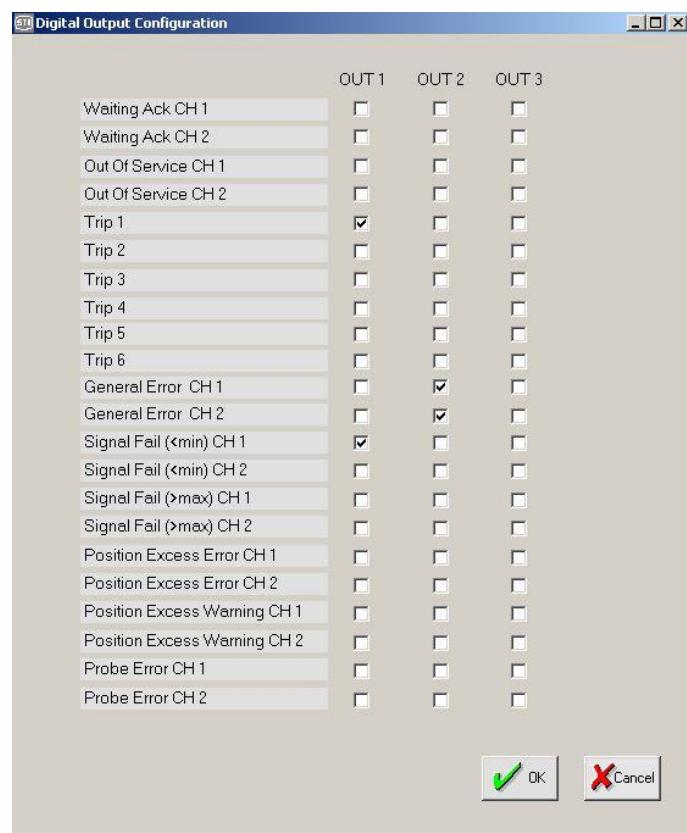
Digital Output



Three Digital Output are available, for each one it is possible to select different activation options.

When a Digital Output is configured it is Turned ON (the normally open contact of the relay is closed) if the error condition is not present and it is turned off when the error condition is true.

Selecting more than one error condition in one column the output is turned off when at least one condition is verified.



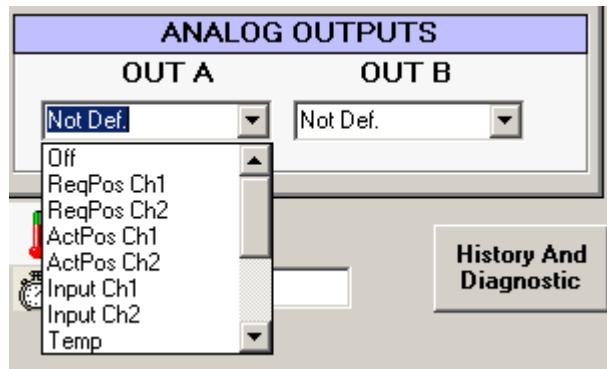


Analog Outputs

Two analog outputs are available.

It's possible to choose the required parameter, in order to associate it to the selected output channel for the reproduction of the indicated signal in a range from 4mA to 20 mA.

- ReqPosCh1 : required position of CH1 , between 4÷20 mA
- ReqPosCh2 : required position of CH2 , between 4÷20 mA
- ActPosCh1 : actuator position of CH1 , between 4÷20 mA
- ActPosCh2 : actuator position of CH2 , between 4÷20 mA
- InputCh1 : input signal of CH1 , between 4÷20 mA
- InputCh2 : input signal of CH2 , between 4÷20 mA
- Temperature :temperature in the controller box , between 0÷100°C
- AI1 : Analog input 1 , between 4÷20 mA
- AI2 : Analog input 2 , between 4÷20 mA
- AI3 : Analog input 3 , between 4÷20 mA
- AI4 : Analog input 4 , between 4÷20 mA
- AI5 : Analog input 5 , between 4÷20 mA
- AI6 : Analog input 6 , between 4÷20 mA





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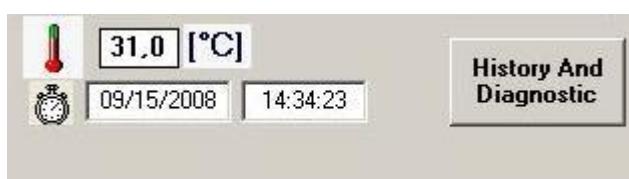
Temperature

Show the temperature inside the enclosure.

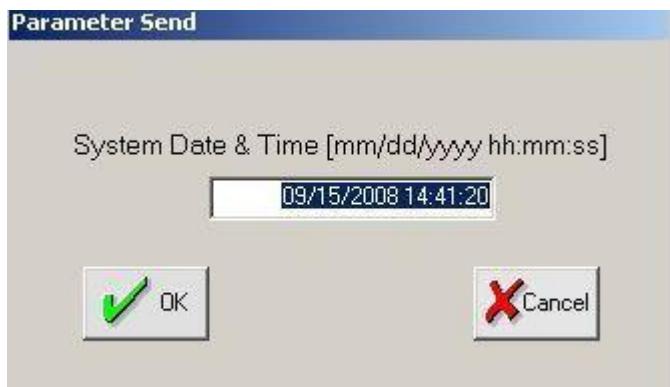
Date & Time

Show Date & Time of the controller.

This information is used for diagnostic purposes.



With a double-click it is possible to change the date&time (when you double-click a panel with actual date&time –taken from the laptop - is opened, pressing 'OK' this information is sent to the controller).





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History and Diagnostic

Different level of diagnostic data are available.

- Counters
- Historic event log
- Periodic log (SD Card)
- Event log (SD Card)

COUNTERS

Historic Event Log

Diagnostic

CH 1			CH 2			EVENT LOG																																																										
Error Counters			Error Counters			<table border="1"> <tr><td>09/17/2008 11:01:11</td><td>System Turned ON</td></tr> <tr><td>09/17/2008 10:14:14</td><td>Trip 1</td></tr> <tr><td>09/17/2008 09:18:32</td><td>System Turned ON</td></tr> <tr><td>09/17/2008 09:11:59</td><td>System Turned ON</td></tr> <tr><td>09/16/2008 18:52:01</td><td>Ch2 Probe Error</td></tr> <tr><td>09/16/2008 17:49:30</td><td>Ch1 Calibration Aborted</td></tr> <tr><td>09/16/2008 17:48:32</td><td>System Turned ON</td></tr> <tr><td>09/16/2008 17:39:45</td><td>System Turned ON</td></tr> <tr><td>09/16/2008 17:38:19</td><td>Ch2 Probe Error</td></tr> <tr><td>09/16/2008 16:45:07</td><td>Trip 1</td></tr> <tr><td>09/16/2008 15:56:45</td><td>Trip 1</td></tr> <tr><td>09/16/2008 15:54:38</td><td>Trip 1</td></tr> <tr><td>09/16/2008 15:26:04</td><td>Ch1 Calibration completed</td></tr> <tr><td>09/16/2008 15:10:13</td><td>System Turned ON</td></tr> <tr><td>09/16/2008 15:10:10</td><td>Ch2 Probe Error</td></tr> <tr><td>09/16/2008 15:10:06</td><td>System Turned ON</td></tr> <tr><td>09/16/2008 15:01:27</td><td>Ch2 System out of service</td></tr> <tr><td>09/16/2008 14:46:08</td><td>Ch1 Position Excess Warning</td></tr> <tr><td>09/16/2008 14:45:54</td><td>Trip 1</td></tr> <tr><td>09/16/2008 14:43:32</td><td>Ch1 System out of service</td></tr> <tr><td>09/16/2008 14:43:28</td><td>Ch2 System in service</td></tr> <tr><td>09/16/2008 14:38:07</td><td>Ch2 System out of service</td></tr> <tr><td>09/16/2008 14:37:43</td><td>Ch2 System in service</td></tr> <tr><td>09/16/2008 14:37:35</td><td>Ch1 System in service</td></tr> <tr><td>09/16/2008 14:36:46</td><td>Ch1 System out of service</td></tr> <tr><td>09/16/2008 14:36:12</td><td>Ch1 System in service</td></tr> <tr><td>09/16/2008 14:34:52</td><td>Ch1 System out of service</td></tr> <tr><td>09/16/2008 14:33:35</td><td>Ch1 System in service</td></tr> </table>			09/17/2008 11:01:11	System Turned ON	09/17/2008 10:14:14	Trip 1	09/17/2008 09:18:32	System Turned ON	09/17/2008 09:11:59	System Turned ON	09/16/2008 18:52:01	Ch2 Probe Error	09/16/2008 17:49:30	Ch1 Calibration Aborted	09/16/2008 17:48:32	System Turned ON	09/16/2008 17:39:45	System Turned ON	09/16/2008 17:38:19	Ch2 Probe Error	09/16/2008 16:45:07	Trip 1	09/16/2008 15:56:45	Trip 1	09/16/2008 15:54:38	Trip 1	09/16/2008 15:26:04	Ch1 Calibration completed	09/16/2008 15:10:13	System Turned ON	09/16/2008 15:10:10	Ch2 Probe Error	09/16/2008 15:10:06	System Turned ON	09/16/2008 15:01:27	Ch2 System out of service	09/16/2008 14:46:08	Ch1 Position Excess Warning	09/16/2008 14:45:54	Trip 1	09/16/2008 14:43:32	Ch1 System out of service	09/16/2008 14:43:28	Ch2 System in service	09/16/2008 14:38:07	Ch2 System out of service	09/16/2008 14:37:43	Ch2 System in service	09/16/2008 14:37:35	Ch1 System in service	09/16/2008 14:36:46	Ch1 System out of service	09/16/2008 14:36:12	Ch1 System in service	09/16/2008 14:34:52	Ch1 System out of service	09/16/2008 14:33:35	Ch1 System in service
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Position History			Position History			<table border="1"> <tr><td>0h 02m 41s</td><td>0h 01m 55s</td></tr> <tr><td>76h 07m 00s</td><td>0h 15m 46s</td></tr> <tr><td>0h 41m 25s</td><td>0h 02m 45s</td></tr> <tr><td>8h 38m 45s</td><td>0h 37m 25s</td></tr> <tr><td>0h 28m 17s</td><td>73h 51m 54s</td></tr> <tr><td>0h 00m 19s</td><td>8h 01m 50s</td></tr> <tr><td>0h 00m 03s</td><td>0h 00m 00s</td></tr> <tr><td>74h 55m 16s</td><td>72h 52m 21s</td></tr> </table>			0h 02m 41s	0h 01m 55s	76h 07m 00s	0h 15m 46s	0h 41m 25s	0h 02m 45s	8h 38m 45s	0h 37m 25s	0h 28m 17s	73h 51m 54s	0h 00m 19s	8h 01m 50s	0h 00m 03s	0h 00m 00s	74h 55m 16s	72h 52m 21s																																								
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						Temperature [°C] <table border="1"> <tr><td>Min</td><td>300</td></tr> <tr><td>Max</td><td>390</td></tr> <tr><td>Average</td><td>320</td></tr> </table>			Min	300	Max	390	Average	320																																																		
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Average	320																																																															

Counters :

The controller record the number of time that an event happens and the last time and date of this event.
Events are grouped in three main groups : Channel 1, Channel 2 and Alarm Counters



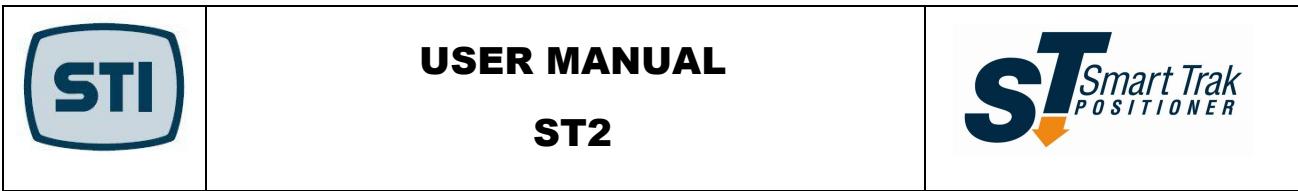
Press the 'download' button to get data from the positioner



Press the 'Report' button to make a file (in .rtf format) with all the data



Press the 'Exit' button to close the window



Example of Diagnostic Report :

Report Date : 13/10/2008 15.20

CHANNEL 1

Error Counter Date

Signal <min	:	0
Pos.Exc.Error	:	0
Pos.Exc.Warn.	:	0
Probe	:	2 10/10/2008 18:31:11
Hard Limits	:	0
Calib. Erased	:	0
Calibr. Aborted	:	0

System Counter Date

Calibration	:	0
In Service	:	0
Out Of Service	:	0

Position History

Total Stroke (Stroke nr.)	:	0h 00m 12s
Time in [0,1)	:	6h 07m 30s
Time in [1,25)	:	0h 04m 25s
Time in [25,50)	:	0h 00m 00s
Time in [50,75)	:	0h 00m 00s
Time in [75,99)	:	0h 00m 00s
Time in [99,100)	:	0h 00m 05s
In Service Time	:	0h 00m 00s

CHANNEL 2

Error Counter Date

Signal <min	:	0
Pos.Exc.Error	:	0
Pos.Exc.Warn.	:	0
Probe	:	2 10/10/2008 18:31:11
Hard Limits	:	0
Calib. Erased	:	0
Calibr. Aborted	:	0

System Counter Date

Calibration	:	0
In Service	:	0
Out Of Service	:	0

Position History

Total Stroke (Stroke nr.)	:	0h 00m 06s
Time in [0,1)	:	6h 12m 00s
Time in [1,25)	:	0h 00m 00s
Time in [25,50)	:	0h 00m 00s
Time in [50,75)	:	0h 00m 00s
Time in [75,99)	:	0h 00m 00s
Time in [99,100)	:	0h 00m 00s
In Service Time	:	0h 00m 00s

Alarm Counter Date

Trip 1	:	0
Trip 2	:	0



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Trip 3 : 0
Trip 4 : 0
Trip 5 : 0
Trip 6 : 0
Error on SOV 1 : 0
Error on SOV 2 : 0
Error on SOV 3 : 0
Error on SOV 4 : 0
Error on SOV 5 : 0
Error on SOV 6 : 0
EEPROM 0 : 0
EEPROM 1 : 0

Temperature [°C]

Min : 23.2
Max : 36.0
Average : 33.7

Events Log

10/13/2008 15:18:20 Log Time: 10 --> 2
10/13/2008 15:16:11 Log Time: 0 --> 10
10/13/2008 12:27:41 System Turned ON
10/10/2008 18:31:11 Ch1 Probe Error
10/10/2008 18:31:11 Ch2 Probe Error
10/10/2008 18:26:46 System Turned ON
10/10/2008 18:26:00 Ch2 Probe Error
10/10/2008 17:19:11 SOV3: Channel 1 --> Channel 2
10/10/2008 17:18:42 SOV2: Channel 1 --> Channel 2
10/10/2008 17:01:41 Trip 2 Err Mode: Off --> SSD1
10/10/2008 16:53:47 Ch1 Operation Mode: Stem Out --> Stem In
10/10/2008 16:53:41 Ch1 Operation Mode: Stem In --> Stem Out
10/10/2008 16:46:38 Ch1 HighLimit: 95,0 --> 96,0
10/10/2008 16:46:33 Ch1 LowLimit: 5,3 --> 5,0



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Historic event log

Up to 500 events can be stored in the internal eeprom of the positioner.

The events are stored in a circular queue, so when the limit is reached the older elements are deleted to free space for the new elements.

Each element is recorded with : date, time, event specification.

Start Read

Press the 'Start Read' button to download the events from the positioner.

Events are downloaded starting from the most recent one.

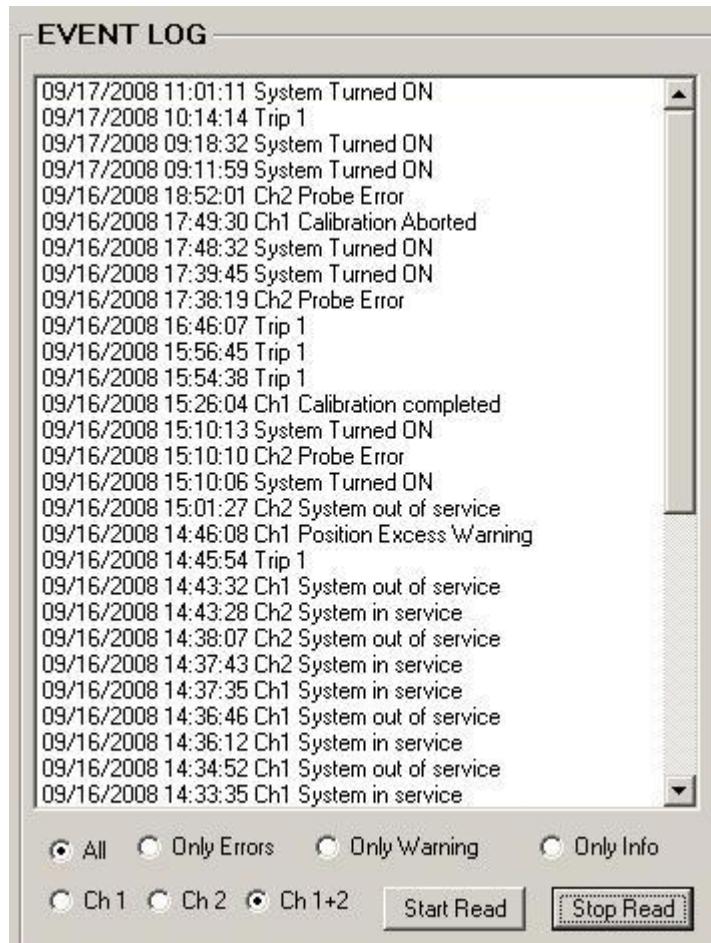
Stop Read

Press the 'Stop Read' button to stop the download.

Filter options are available to show only :

- Errors
- Warning
- Info

It is also possible to select a filter related to the channel : only Ch1, only Ch2, Ch1 & Ch2



Types of event :

- Ch x Signal < min
- Ch x Signal > max
- Ch x Position Error
- Ch x Position warning
- Ch x Probe Error
- Ch x Hard Limit
- Ch x Calibration Erased
- Ch x Calibration Aborted
- Ch x Calibration Completed
- In Service
- Out Of Service
- Trip x
- Error On SOV x
- Eeprom x
- System Startup



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Periodic log (SD Card)

Inserting an SD Card in the slot an automatic process of data collection is activated.

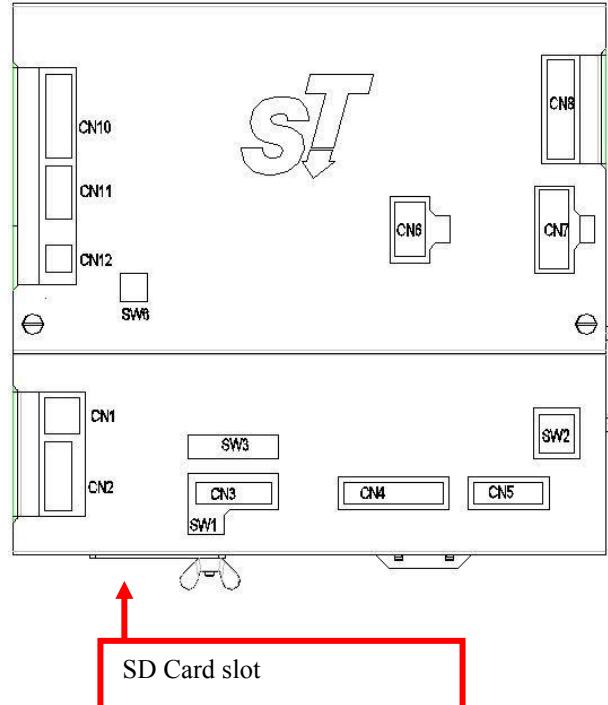
The time between two consecutive recording is defined in the SDCARD LogTime parameter in the advanced STI menu. Typically the LogTime is equal to 10 minutes.

A file is created for each month of the year, the name of the file is DIAGyyymm (where 'yy' is the year and 'mm' is the month).

The Graph Tool allow :

- To open the History file and show the most important data
- To convert the History file in a .csv file (compatible with Excell and other spreadsheet)

Converting the History file you have access up to 30 different data to monitor the status of a positioner.



SDCard :

ST is able to manage standard SDCard formatted in FAT16 (storage capacity up to 2Gbyte). In the STI advanced panel it is possible to check if the SD is recognized or not.



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Event log (SD Card)

- Every time an event happens a SnapShot is saved on the SD card
- SnapShot is 20 seconds lenght with a sample rate of 100Hz
- SnapShot is centered around the event (pretrigger is configurable in the advanced STI menu)
- The RemoteControl Graph tool is able to open and show a SnapShot file
- SnapShot are saved with a name related to date/time/event_type in order to find the data in an easy way

Events that start a snapshot are :

- Ch x Signal < min
- Ch x Signal > max
- Ch x Position Error
- Ch x Position warning
- Ch x Probe Error
- Ch x Hard Limit
- TRIP x

	<p style="text-align: center;">USER MANUAL ST2</p>	
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Main vars and status

This window report a collection of information about the status of the positioner.

You can select 3 different views :



- Channel 1 : only the information of the channel 1
- Channel 2 : only the information of the channel 2
- Channel 1 and 2 : the information of both the channels

ActPos [%] :

Actual position measured by the positioner.

ReqPos [%] :

Request position evaluated (the request position take in account the 'Service State', the 4-20ma input signal or manual setup, the transfer function and the split range)

Input [mA] :

Current read at the 4-20ma Loop current Input channel.



The user can align the value showed using the commands available in the 'CFG' area

Status :

The calibration status is showed

Errors:

Show , for each channel, the actual and the last error. More detailed information are available in the 'history and diagnostic' window.



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Service State / Mode :

Allow the selection of the Service State.

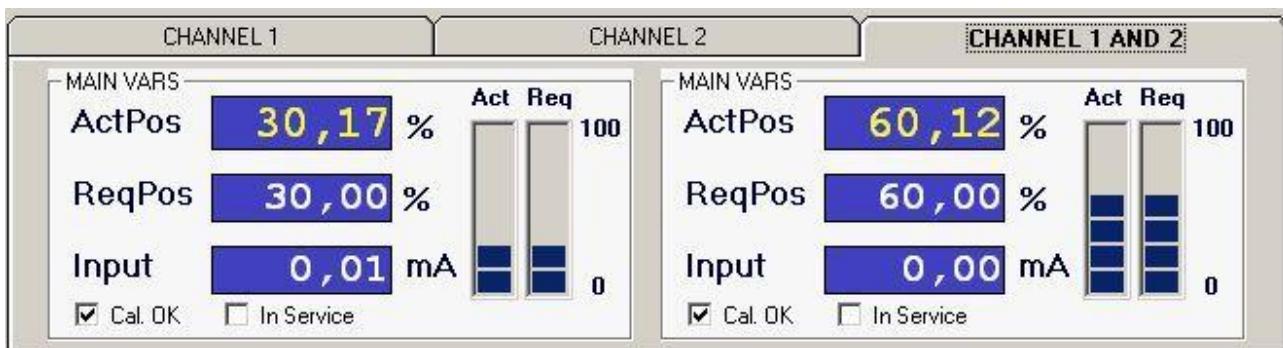
- In Service : the Request Position is evaluated continually by the positioner starting from the 4-20mA signal value
- Out Of Service (Manual) : the Request Position come from the manual set in the window. When the Service Mode become 'Out Of Service (Manual)' the first manual setpoint is equal to the last 'Actual position' in order to minimize the movement of the system
- Out of Service : special mode selected automatically when the system is not calibrated. In this mode port B is fully pressurized and port A is depressurized



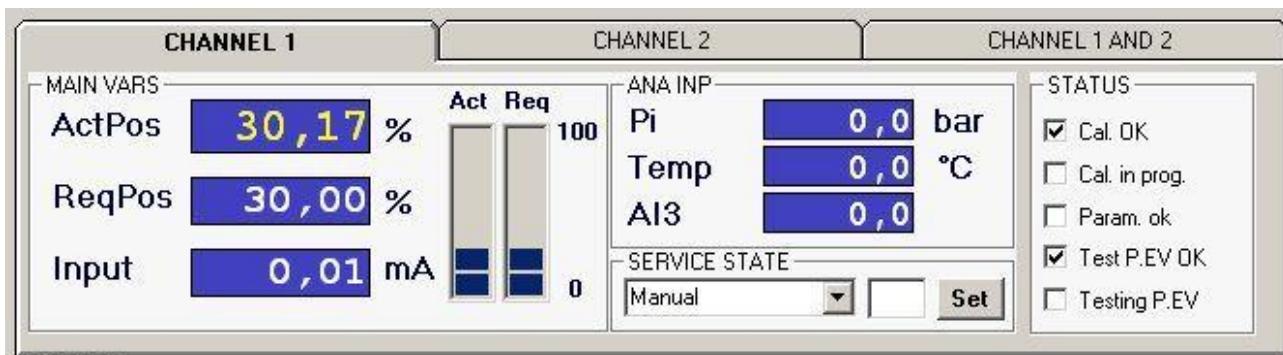
Changing from 'Out of Service' to 'In Service' the system can move

The 'Main vars' window can show information in two ways :

Channel 1 & 2 : reduced set of information concerning the two channels in one page



Only one channel : detailed information for one channel at a time



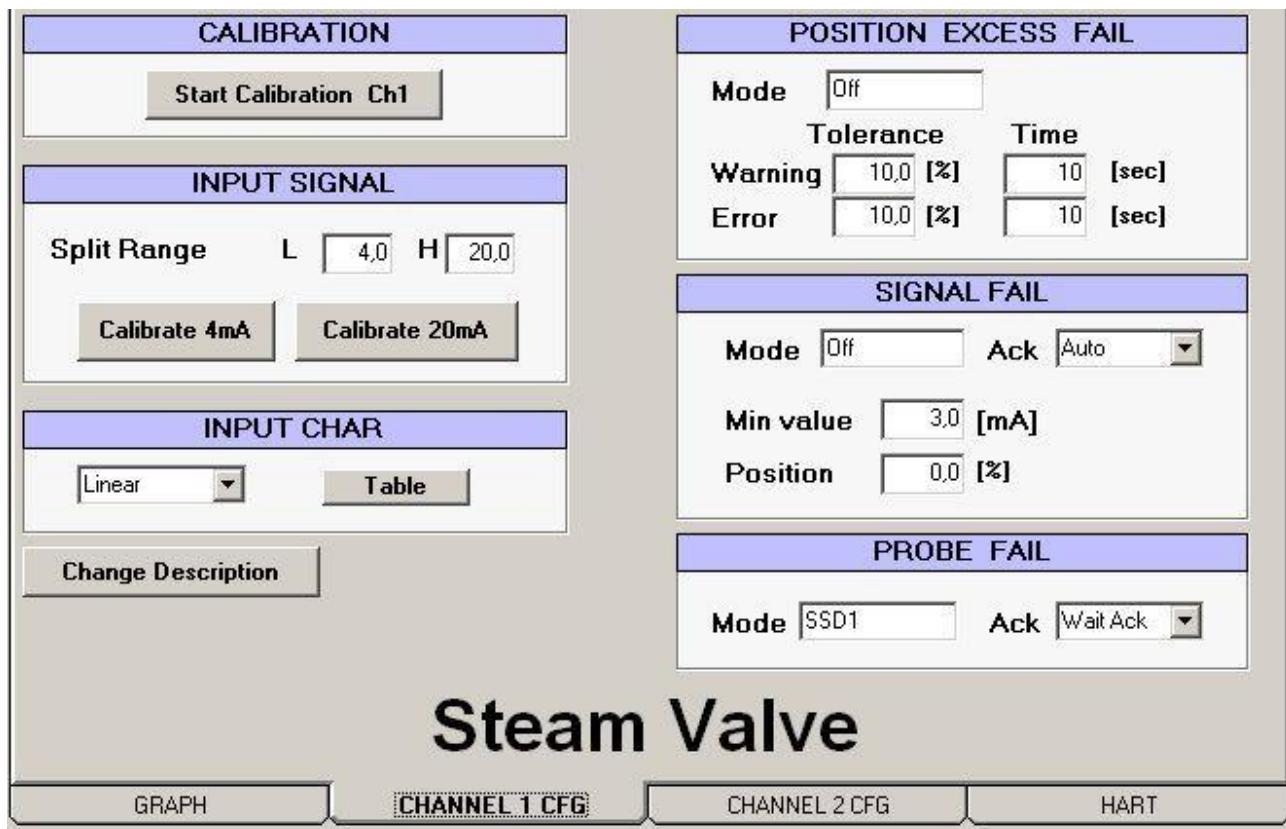


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Channel 1 CFG window (Channel 2 CFG window)



CALIBRATION

Start the calibration procedure.

WARNING

When the 'Start Calibration' button is pressed the system can move.

INPUT SIGNAL : Split range

Enable the split range function.

The values in Lower range value and Upper range value are referred to the 4-20mA input.

A minimum distance of 20% is required between Lower and Upper value, so up to 5 split range area can be configured in different concatenated positioners.

The result of the split range is then evaluated by the 'Transfer Function Curve'.

If the Low range value is equal to 0% and Upper range value is equal to 100% the positioner interpret 4ma like the 0% Request position and the 20ma like 100%.

If the Low range value is equal to 0% and Upper range value is equal to 50% the positioner interpret 4ma like the 0% Request position and the 12ma like 100%.



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INPUT SIGNAL : Calibrate 4mA

Read the actual value of the input current and assume it like 4ma value.

⚠ CAUTION

Be sure that you are supplying the positioner with a stable, real 4ma

INPUT SIGNAL : Calibrate 20mA

Read the actual value of the input current and assume it like 20ma value.

Change Description

Each channel can have a description used to identify it in an easy way.



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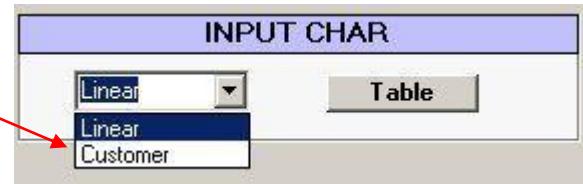
INPUT CHAR.

The Characterization specify the relationship between the Input signal and the Request Position.

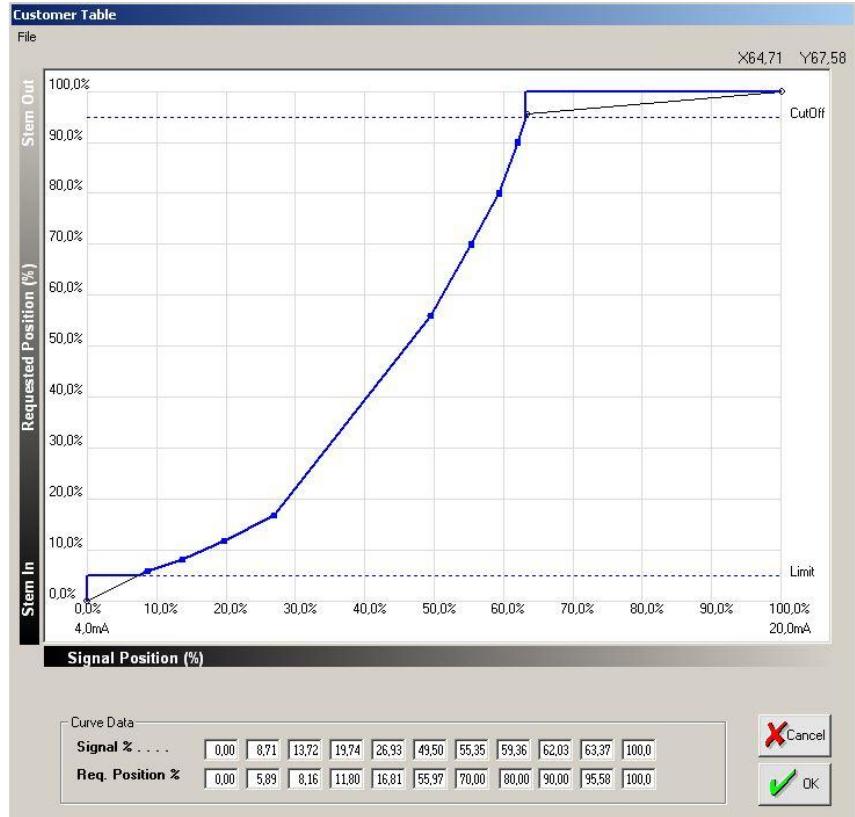
Selecting 'Customer' you have the chance to draw a specific characterization curve.

Table button :

Open the Transfer Function Curve window



- The 'Stem In' and 'Stem Out' label in the 'Requested position' axis show the effect of the '0 Ctrl Signal' and '0 Ctrl Position' selection
- The '4.0mA' and '20.0mA' in the 'Signal Position' show the effect of the 'Split Range' setup
- The effect of 'Limit' and 'CutOff' are showed on the graph
- To 'Send' a 'Customer Curve' to the Positioner press the 'OK' button.
 - You can change a value in the table or click & move the dot in the graph
 - Keeping hold the shift key and clicking on two dots, automatically the system make a linear interpolation between these two points.





Position excess Fail

Selecting this command, it's possible to configure the max admissible position error and warning (difference between the required and the actual position) and the actions to be executed, if these limits are exceeded.

- **Mode** : configure the action that will be taken when the error happens.
- **Warning Tolerance** : it's possible to set the max error position value (tolerance) that cause a warning
- **Warning Time** : In case of warning condition, this parameter defines the waiting time before the alarm is activated
- **Error Tolerance** : it's possible to set the max error position value (tolerance) that cause an error
- **Error Time** : In case of error condition, this parameter defines the waiting time before the alarm is activated

POSITION EXCESS FAIL			
Mode	Off	Tolerance	Time
Warning	10,0 [%]	10	[sec]
Error	10,0 [%]	10	[sec]

To set the value, double click on the corresponding cell, click the option and press "OK" to confirm it or "CANCEL" to exit.

Signal Fail

This command allows to configure the minimum and maximum admissible inlet signal (mA), the actions to be executed if these limits are reached and the error clearing condition.

Mode : The first line allows to configure the action to be executed in case of an out of range or fail signal.

To set the value, double click on the corresponding cell, click the option and press "OK" to confirm it or "CANCEL" to exit.

Ack : The end mode option configures the action to be executed at the end of the error conditions.

The available options are:

- AUTO Automatic return to normal working condition without waiting for confirmation.
- WAIT ACK A confirmation is required before returning to normal working condition.
- WAIT NOERR Automatic return to normal working condition only if all

SIGNAL FAIL			
Mode	Off	Ack	Auto
min	3,0	max	22,0
Limits [mA]			
Position	0,0	[%]	

Position :

This function is active only if the "Spool" selection has been made for the "Error mode" option; by this function it's possible to define the actuator position in case of signal fail.

The value of the position (expressed in percentage of the stroke) can be adjusted between -10 and 110% of the stroke,



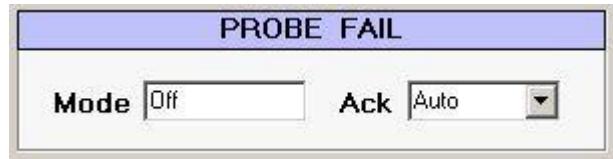
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Probe Fail

Mode : The first line allows to configure the action to be executed in case of an out of range or fail of the probe. To set the value, double click on the corresponding cell, click the option and press “OK” to confirm it or “CANCEL” to exit.



Ack : The end mode option configures the action to be executed at the end of the error conditions. The available options are:

- AUTO Automatic return to normal working condition without waiting for confirmation.
- WAIT ACK A confirmation is required before returning to normal working condition.
- WAIT NOERR Automatic return to normal working condition only if all



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HART panel

HART PARAMETERS

Tag :

The Tag is a 8 character label assigned by the end user based on the location and use of the field device. It's a 8 character (6 byte) Packed ASCII string used to identify the field device. The term originated when physical tags were attached to instruments for this purpose.

HART PARAMETERS		HART COMMUNICATION	
Tag	STID8FT	Date	01/01/2000
Descriptor			
Message			
Polling Address	0	Dev. ID	1
Poll Device			
HART PROTOCOL			
Long Frame Address:	D882000001		
Command:	33	Response Code:	00
Error Code:	00	Device Status:	40

Date :

The date is represented by three 8-bit binary unsigned integers representing, respectively, the day, month and year (minus 1900). It's a date code, used by the Master for record keeping (e.g. last or next calibration date).

Descriptor :

The Descriptor is a 16 character (12 byte) Packed ASCII string used by the Master for record keeping. The default value is a blanked string, 16 bytes long.

Message :

The Message is a 32 character (24 byte) Packed ASCII string used by the Master for record keeping. The default value is a blanked string, 32 bytes long.

Polling address:

In the HART Protocol, the polling address is an integer used to identify the field device. It is used to construct the Short Frame Address. The Polling Address is set to 0 in point to point installations.

Dev. ID :

This number is different for every device manufactured with a given Manufacturer ID and Device Type.

HART Protocol

Show some communication parameters used for debug

HART Communication

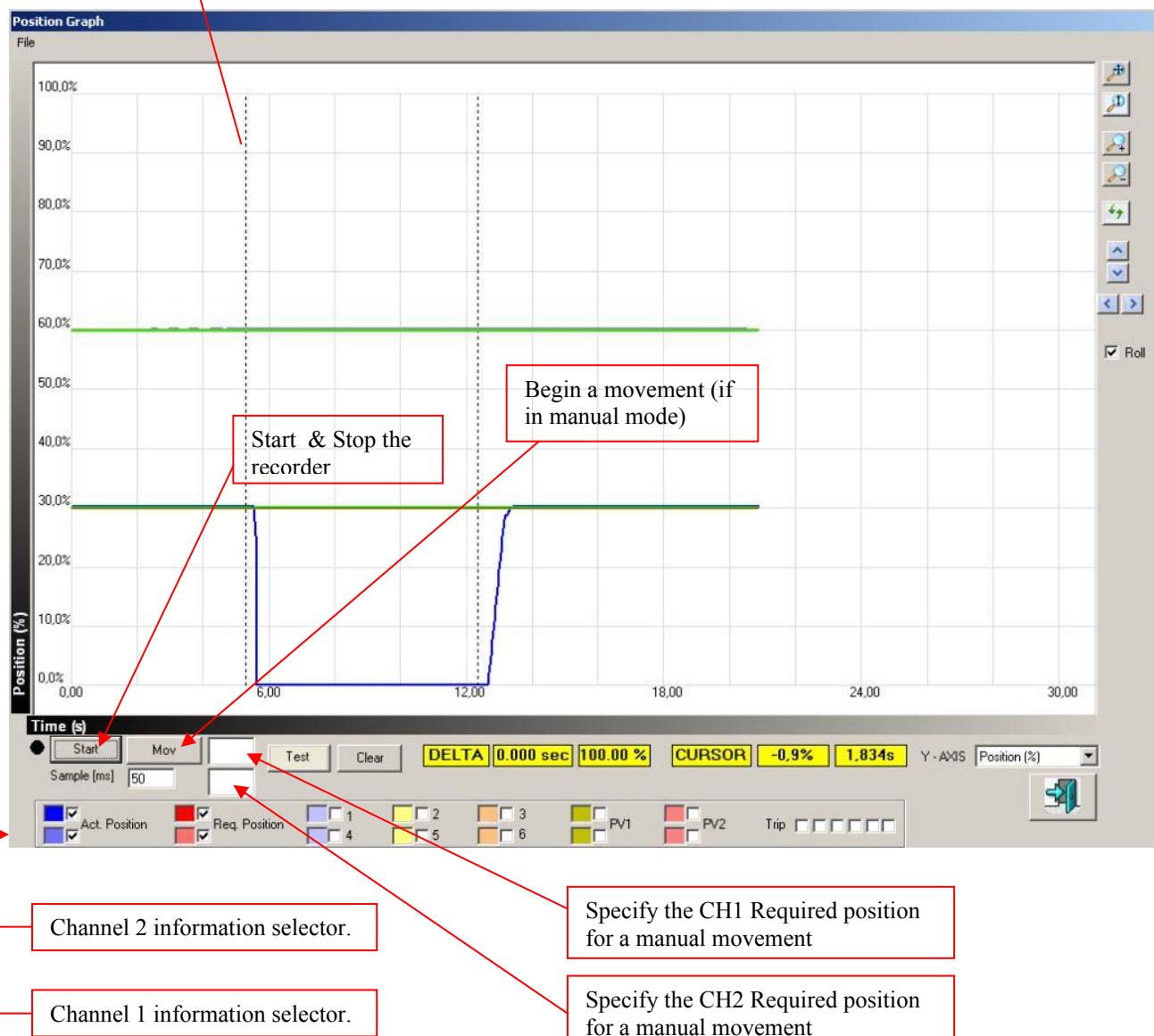
Hart Mode :

'Time management' and 'Time management (performance)' are two different way to manage the Hart modem. If you have experience of communication problems try to change this option.



The Graph window

Event Line : moving with the mouse on the line, specification about the event are showed (i.e. Ch1 TRIP1)



Double Click on the painted area to change the color.



The Graph Menu

File : Save Image

Save the actual showed picture like a .bmp file

File : Save Snapshot

Save the actual picture in binary file

File : Load Snapshot

Load the graph stored in a binary file

File : Load History File

Load an History file previously stored in a SD card

Opening the file you can select the portion of the graph that you want to see.

In the right-bottom side of the graph appear a selection box with a list of the records available. Select the desidered one and click Load to open.



File : Convert History File

Open an History file previously stored in a SD card in a .csv file. It is possible open the file with a spreadsheet like Excel and analyze the data.



USER MANUAL

ST2



STI Advanced Panel

This panel is for expert user only.

Inserting the password '23456' the 'STI' button appear in the top left part of the main window.

Pressing the 'STI' button different windows are available



USER MANUAL

ST2

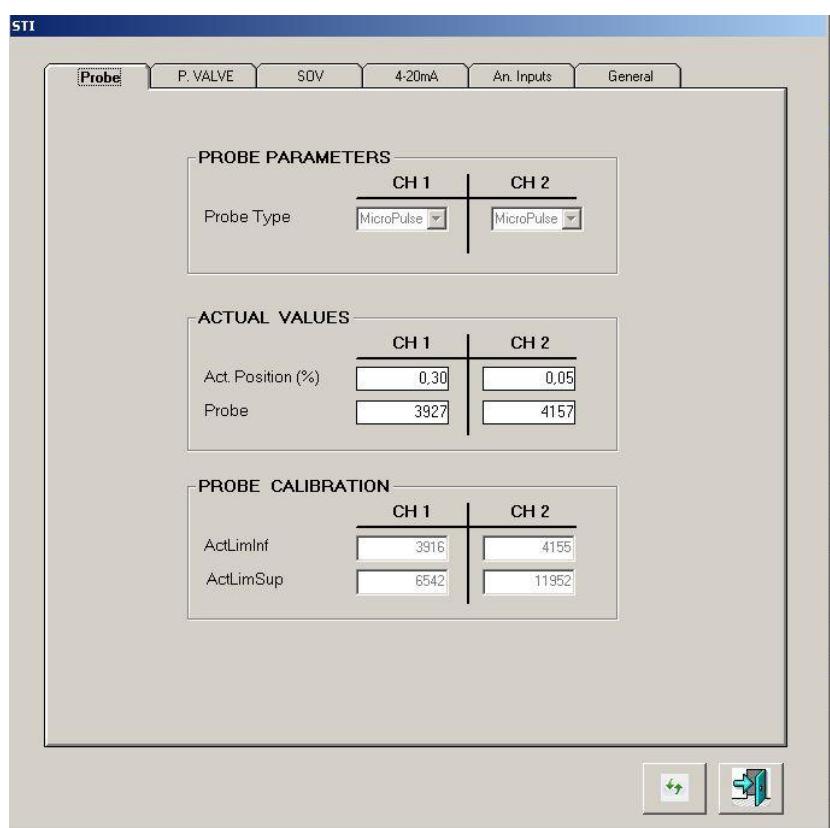


Probe (STI Advanced Panel)

For each channel is possible :

- Select the type of the probe
 - o Micropulse
 - o 4-20mA
- Check the actual values
- Verify calibration limits

It is possible to change the type of the probe only if the channel is NOT calibrated.





USER MANUAL

ST2



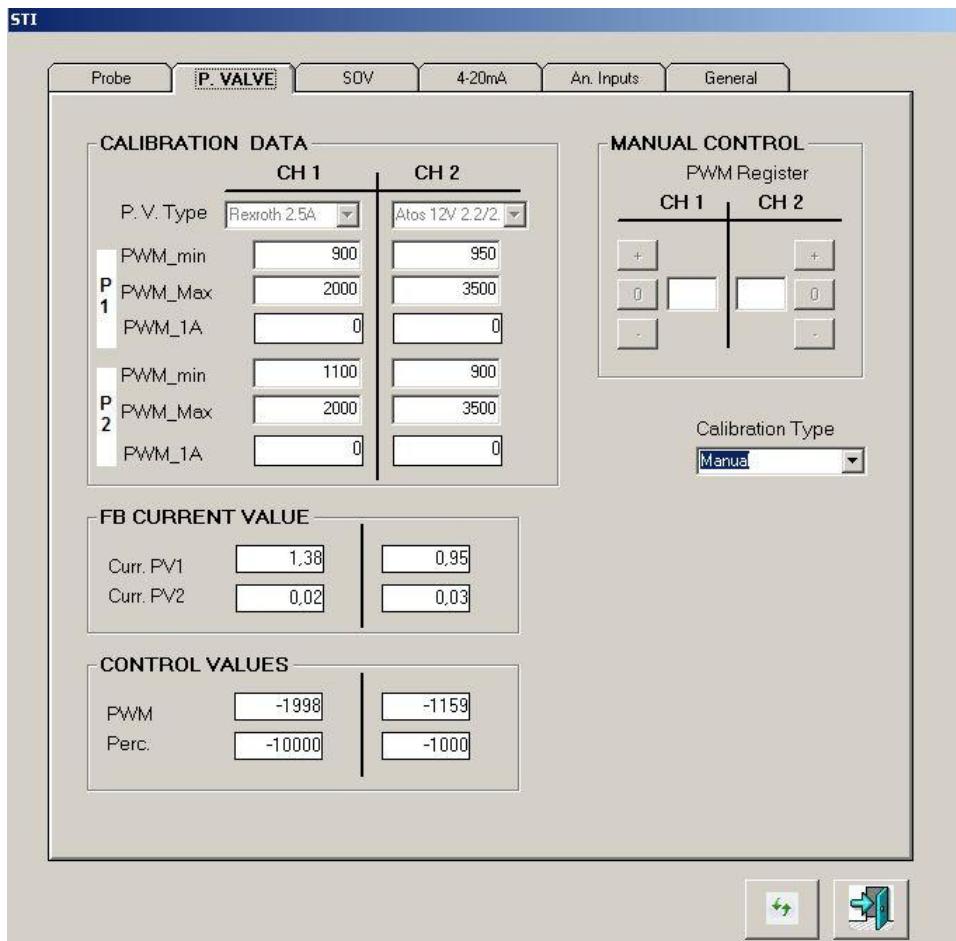
Proportional valve (STI Advanced Panel)

The P.V.Type allow the selection of different types of proportional solenoid valve. Choosing a value the PWM min and max limits are loaded.

If it is needed to use a proportional valve not listed, it is possible to evaluate the min and max value with manual control and then put the value in the min and max field (select calibration type equal to 'Manual' to disable the self evaluation of the current limits).

FB Current Value :

Show the current (in ampere) that flow in the solenoid valve.



Manual control :

(only if the channel is not calibrated)

Drive manually one proportional valve.

Write a value in the field (between the PWMmin and max values) and press the '+' or '-' button to energize the proportional valve in one direction or in the other.

Check the current that energize the solenoid in the 'FB Current Value' field.

Calibration type :

Manual : during calibration only the minimum current needed to move the valve is evaluated

Autosearch : during calibration not only the minimum current is evaluated but also the PWM needed to reach the nominal current value (if you select an ATOS 12V 2,2A the ST2 search for the PWM that is necessary to drive 2,2A in the coil).



USER MANUAL

ST2



SOV (STI Advanced Panel)

Feedback :

The 'SET' column show if the ST2 want to energize a specific solenoid valve(The yellow led is turned 'ON').

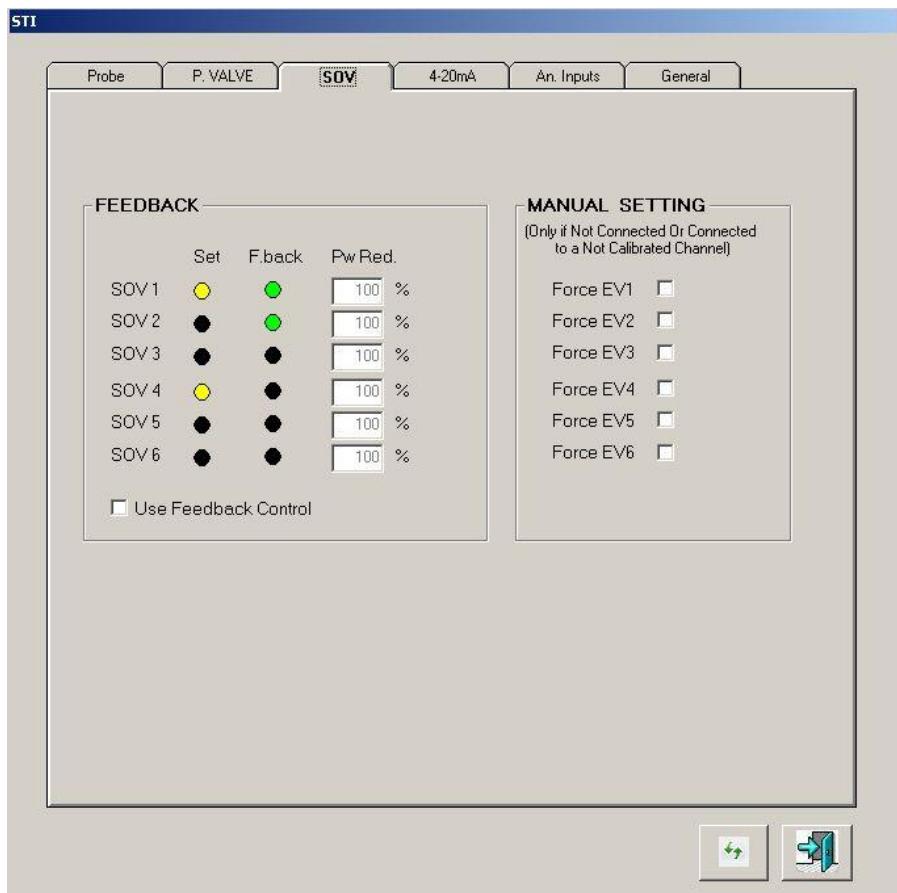
The 'F.back' column show if a solenoid valve is connected without errors (the GREEN led is turned 'ON' if a solenoid valve is recognized).

'Pw Red.'

Select the power level for the SOV. A solenoid valve is energized with the full power (24V=). After 1 second the power applied is equal to the percentage specified in the field. Reducing the power (for example at 80%) the life of a solenoid valve is longer, the heating is reduced and the total power used for the device is less. In case of long cables between ST2 and SOV it is important to check that the voltage on the coil is enough)

'Use Feedback Control'

Checking the box if an error happens on a SOV it is managed by the ST2



Manual Settings

If the SOV is not assigned to a calibrated channel it is possible to turn ON and OFF it.



USER MANUAL

ST2



4-20mA (STI Advanced Panel)

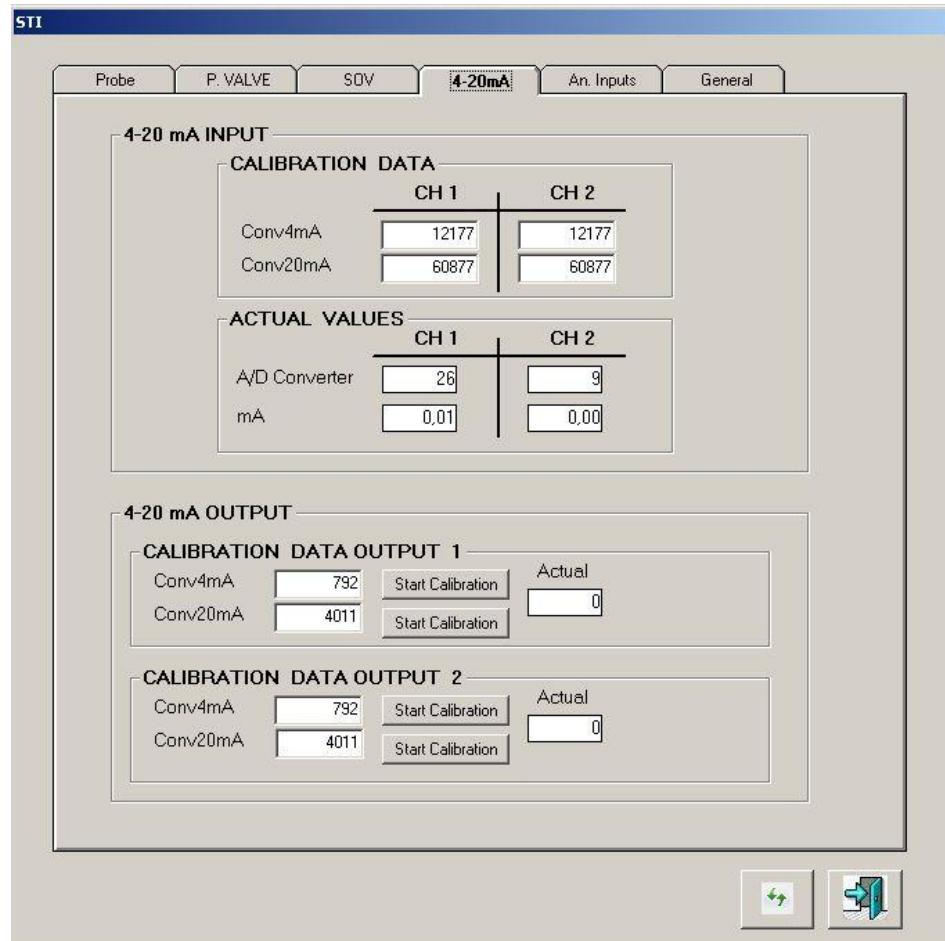
4-20mA INPUT :

It is possible to check the calibration limits and the current value

It is possible to calibrate the 4-20mA input in the standard channel CFG panel.

4-20mA OUTPUT :

It is possible to calibrate the 4mA and the 20mA signal level of each output.

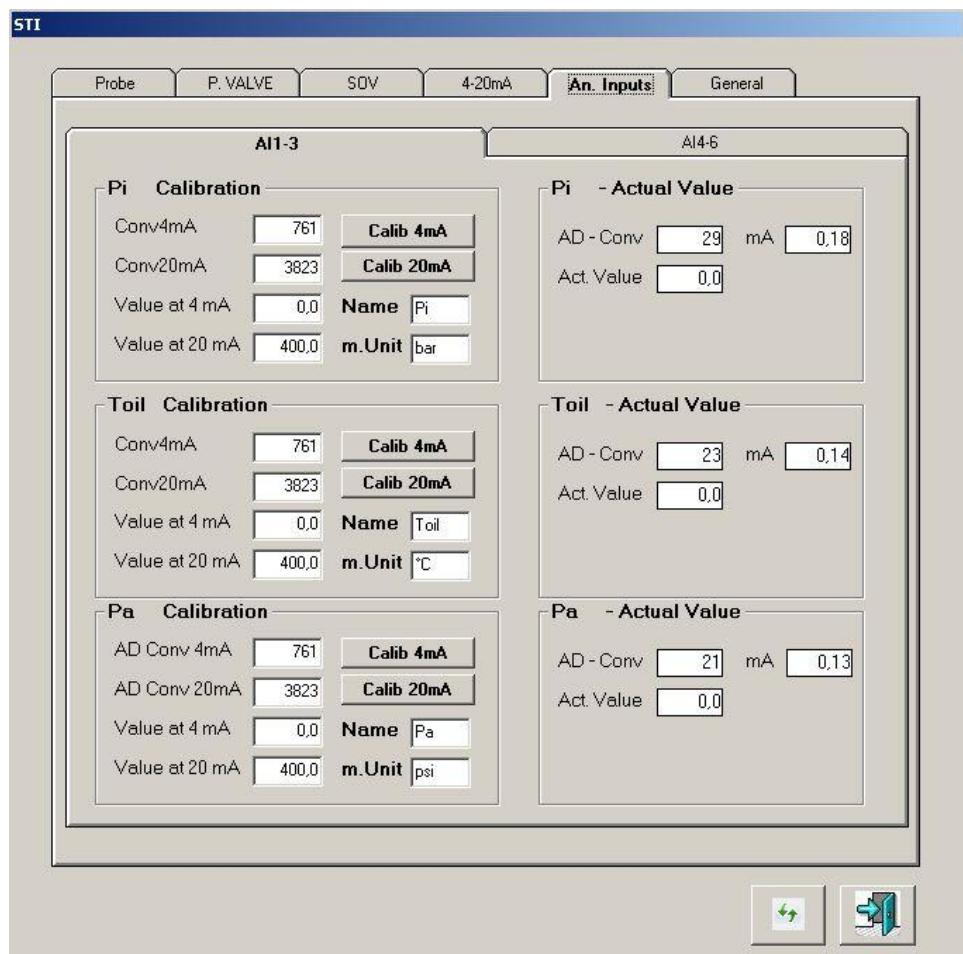




An. Inputs (STI Advanced Panel)

For each analog input (6 channels are available) it is possible :

- Calibrate the 4mA limit
- Calibrate the 20mA limit
- Assign a Name of 4 digit (for example 'Pi')
- Assign a label like measuring unit (for example 'bar')
- Specify the relationship between the 4-20mA signal and the measured value (for example : 4mA=0bar, 20mA=400bar)





USER MANUAL

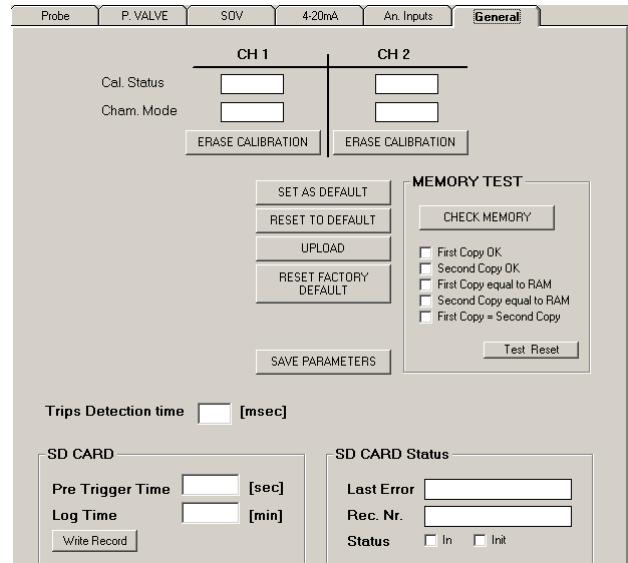
ST2



General (STI Advanced Panel)

'Erase calibration' :

For each channel it is possible to remove the calibration



'Set as default' :

Save the actual configuration data like a default in the ST2 memory.

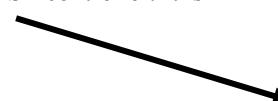


'Reset to default' :

Load a stored configuration. It is possible to select a partial set of data to load.

'Upload' :

Send the actual data in the Remote Control to the ST controller. It is possible to select a partial set of data to load.

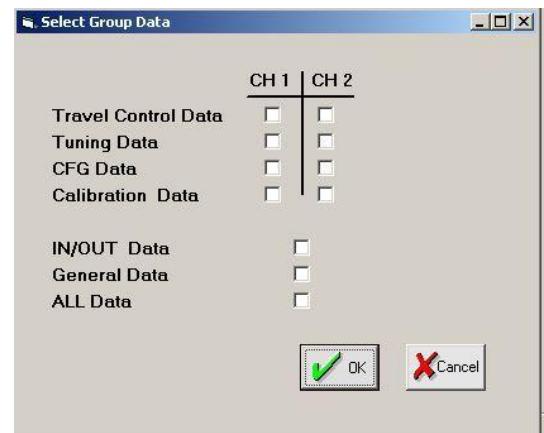


'Reset factory default' :

Reset the ST2 to the factory default data.

'Save parameters' :

Start to save the parameters that are in RAM in the eeprom (this action is only for diagnostic, the parameters are saved automatically when changed in the RemoteControl interface).



'Memory test' :

With the 'check memory' button it is possible to check if the stored configuration is equal to the one used. This option is for diagnostic purpose

'Trips detection time' :

Specify the delay (filter) in milliseconds for TRIP detection.

SD CARD : Pre Trigger Time

Position of the event in the 20 seconds snapshot. Selecting 8 sec the snapshot starts 8 second before the event.

SD CARD : Log Time

Period between two consecutive record in the Periodic Log



USER MANUAL

ST2



The Menu

Menu : File

Load:

Load a saved set of parameters in the RC interface

Save :

Save the current set of parameters in a .qtp file

Report :

Make a document in .rtf format with the actual parameters (It is similar to the Save command but the file format is compatible with editor software)

Exit :

Close the application

Menu : Device

Download

It is the same of the quick button



	USER MANUAL ST2	
---	----------------------------------	---

Example of Configuration Report



SYSTEM REPORT

SYSTEM INFORMATION		
Date (PC)	08/20/2010 09.02.00	
Date (Smart Trak)	08/20/2010 08:03:33	
Channel 1 Description	Channel 1	
Channel 2 Description	Channel 2	
Device Unique ID	01D1FCC41100009F	
DSP SW Version	9,09	
Temperature	26,0	
	<i>Channel 1</i>	<i>Channel 2</i>
Calibration Status	Not Calibrated	Calibrated
Service State	Out Of Service	Manual

TRAVEL CONTROL		
<i>Parameter</i>	<i>Channel 1</i>	<i>Channel 2</i>
0 Ctrl Signal	Stem In	Stem In
0 Position	Stem In	Stem In
Low Limit	5,0 %	5,0 %
Low Limit Mode	Off	Off
High Limit	95,0 %	95,0 %
High Limit Mode	Off	Off

TUNING		
<i>Parameter</i>	<i>Channel 1</i>	<i>Channel 2</i>
Kp IN	10,0	0,2
Kp Out	10,0	0,2
Stroke Time IN	0,0 sec	0,0 sec
Stroke Time OUT	0,0 sec	0,0 sec
Approach IN	0	0



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Approach OUT	0	0
Dead Band (%)	0,50 %	0,50 %



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FAIL TRIP SETTINGS

Trip Number	Mode Ch1	Mode CH2	Ack	"On" Status
1	Off	Safety Shut Down 4	Auto	Energized
2	Off	Off	Auto	Energized
3	Off	Off	Auto	Energized
4	Off	Off	Auto	Energized
5	Off	Off	Auto	Energized
6	Off	Off	Auto	Energized

SOV ASSIGNEMENT

SOV Number	Assigned to:
1	Channel 2
2	Channel 2
3	Channel 2
4	Disconnected
5	Disconnected
6	Disconnected

SOV STATUS

Channel 1

	SOV 1	SOV 2	SOV 3	SOV 4	SOV 5	SOV 6
Running	--	--	--	--	--	--
Safety Shut Down 1	--	--	--	--	--	--
Safety Shut Down 2	--	--	--	--	--	--
Safety Shut Down 3	--	--	--	--	--	--

Channel 2

	SOV 1	SOV 2	SOV 3	SOV 4	SOV 5	SOV 6
Running	On	Off	Off	--	--	--
Safety Shut Down 4	Off	Off	Off	--	--	--
Safety Shut Down 5	On	On	Off	--	--	--
Safety Shut Down 6	Off	Off	Off	--	--	--



USER MANUAL

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BOOSTER CONFIGURATION

Channel 1

	Mode	Target	Act. Tresh	Dis. Tresh.	Use PV	Trip
Safety Shut Down 1	No	Stem In	50,00	20,00	Yes	Trip 1
Safety Shut Down 2	No	Stem In	50,00	20,00	Yes	Trip 1
Safety Shut Down 3	No	Stem In	50,00	20,00	Yes	Trip 1

Channel 2

	Mode	Target	Act. Tresh	Dis. Tresh.	Use PV	Trip
Safety Shut Down 4	With Enable	Stem Out	50,00	5,00	Yes	Trip 1
Safety Shut Down 5	With Enable	Stem In	50,00	5,00	No	Trip 1
Safety Shut Down 6	No	Stem In	50,00	20,00	Yes	Trip 1



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DIGITAL OUTPUT CONFIGURATION

	OUT 1	OUT 2	OUT 3
Waiting Ack CH 1	Off	Off	Off
Waiting Ack CH 2	Off	Off	Off
Out Of Service CH1	Off	Off	Off
Out Of Service CH1	Off	Off	Off
Trip 1	Off	Off	Off
Trip 2	Off	Off	Off
Trip 3	Off	Off	Off
Trip 4	Off	Off	Off
Trip 5	Off	Off	Off
Trip 6	Off	Off	Off
General Error CH 1	Off	Off	Off
General Error CH 2	Off	Off	Off
Signal Fail CH 1	Off	Off	Off
Signal Fail CH 2	Off	Off	Off
Position Excess Error CH 1	Off	Off	Off
Position Excess Error CH 2	Off	Off	Off
Position Excess Warning CH 1	Off	Off	Off
Position Excess Warning CH 2	Off	Off	Off
Probe Error CH 1	Off	Off	Off
Probe Error CH 2	Off	Off	Off

ANALOG OUTPUTS CONFIGURATION

OUT A	Off
OUT B	Off

CHANNELS CONFIGURATION

Parameter	Channel 1	Channel 2
Split Range Low	4,0 mA	4,0 mA
Split Range High	20,0 mA	20,0 mA
Position Excess Error Fail Mode	Off	Off
Position Excess Error Tolerance	10,0 %	10,0 %
Position Excess Error Time	10 sec	10 sec
Position Excess Warning Tolerance	10,0 %	10,0 %
Position Excess Warning Time	10 sec	10 sec
Signal Fail Mode	Off	Off
Signal Fail Ack	Auto	Auto
Signal Fail Min Value	3,0 mA	3,0 mA
Signal Fail Position	0,0 %	0,0 %
Probe Fail Mode	Safety Shut Down 1	Safety Shut Down 4
Probe Fail Ack	Wait Ack	Wait Ack
Input Char	Linear	Linear



USER MANUAL

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CUSTOMER CURVE DATA

<i>Channel 1</i>		<i>Channel 2</i>	
Signal %	Req. Pos %	Signal %	Req. Pos %
0,00	0,00	0,00	0,00
10,00	10,00	10,00	10,00
20,00	20,00	20,00	20,00
30,00	30,00	30,00	30,00
40,00	40,00	40,00	40,00
50,00	50,00	50,00	50,00
60,00	60,00	60,00	60,00
70,00	70,00	70,00	70,00
80,00	80,00	80,00	80,00
90,00	90,00	90,00	90,00
100,00	100,00	100,00	100,00



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ADVANCED PARAMETERS

PROBE PARAMETERS		
	<i>Channel 1</i>	<i>Channel 2</i>
Probe Type	MicroPulse	4-20mA
Probe Limit Inf.	4160	735
Probe Limit Sup.	11988	3473

PROPORTIONAL VALVE		
	<i>Channel 1</i>	<i>Channel 2</i>
Valve Type	Atos 12V 2.2/2.6A	Atos 12V 2.2/2.6A
Side 1		
PWM_min	1000	1100
PWM_Max	3500	3500
PWM_1A	0	0
Side 2		
PWM_min	1000	1100
PWM_Max	3500	3500
PWM_1A	0	0

SOLENOID VALVE						
	<i>SOV 1</i>	<i>SOV 2</i>	<i>SOV 3</i>	<i>SOV 4</i>	<i>SOV 5</i>	<i>SOV 6</i>
PWM Reduction	100%	100%	100%	100%	100%	100%
Use Feedback Control	Off					

INPUT 4-20 mA		
	<i>Channel 1</i>	<i>Channel 2</i>
AD Converter at 4 mA	12177	12177
AD Converter at 20 mA	60877	60877

OUTPUT 4-20 mA		
	<i>OUT 1</i>	<i>OUT 2</i>
AD Converter at 4 mA	792	792
AD Converter at 20 mA	4011	4011



USER MANUAL
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USER MANUAL

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USER ANALOG INPUTS

Analog Input 1

Name	AI1
Measure Unit	
AD Converter at 4 mA	761
AD Converter at 20 mA	3823
Value at 4 mA	0,0
Value at 20 mA	400,0

Analog Input 2

Name	AI2
Measure Unit	
AD Converter at 4 mA	761
AD Converter at 20 mA	3823
Value at 4 mA	0,0
Value at 20 mA	400,0

Analog Input 3

Name	AI3
Measure Unit	
AD Converter at 4 mA	761
AD Converter at 20 mA	3823
Value at 4 mA	0,0
Value at 20 mA	400,0

Analog Input 4

Name	AI4
Measure Unit	
AD Converter at 4 mA	761
AD Converter at 20 mA	3823
Value at 4 mA	0,0
Value at 20 mA	400,0

Analog Input 5

Name	AI5
Measure Unit	
AD Converter at 4 mA	761
AD Converter at 20 mA	3823
Value at 4 mA	0,0
Value at 20 mA	400,0

Analog Input 6

Name	AI6
Measure Unit	
AD Converter at 4 mA	761
AD Converter at 20 mA	3823
Value at 4 mA	0,0
Value at 20 mA	400,0



USER MANUAL

ST2



GENERAL PARAMETERS		
	Channel 1	Channel 2
Camera Mode	Normal	Inverted
SD CARD		
Pre Trigger Time	8,0 sec	
Log Time	60 min	
TRIPS		
Trips Detection Time	40 mSec	



USER MANUAL ST2



Menu : Password

Login

It is the same of the quick button



Change

To change the password

Menu : ? Info

Information panel with different sw version data.

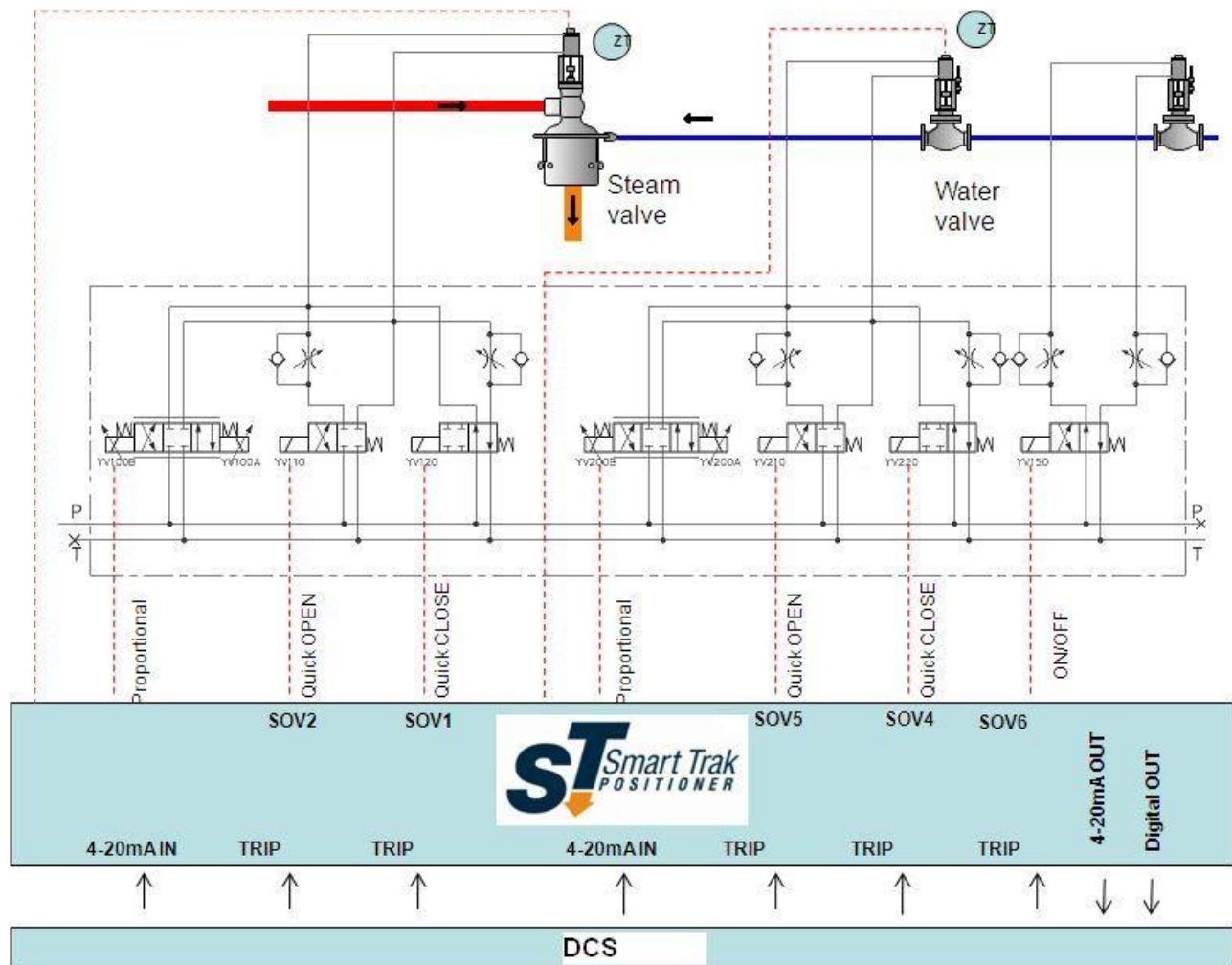
“Device Unique ID” is an hardware identifier used to identify a specific electronic hw.





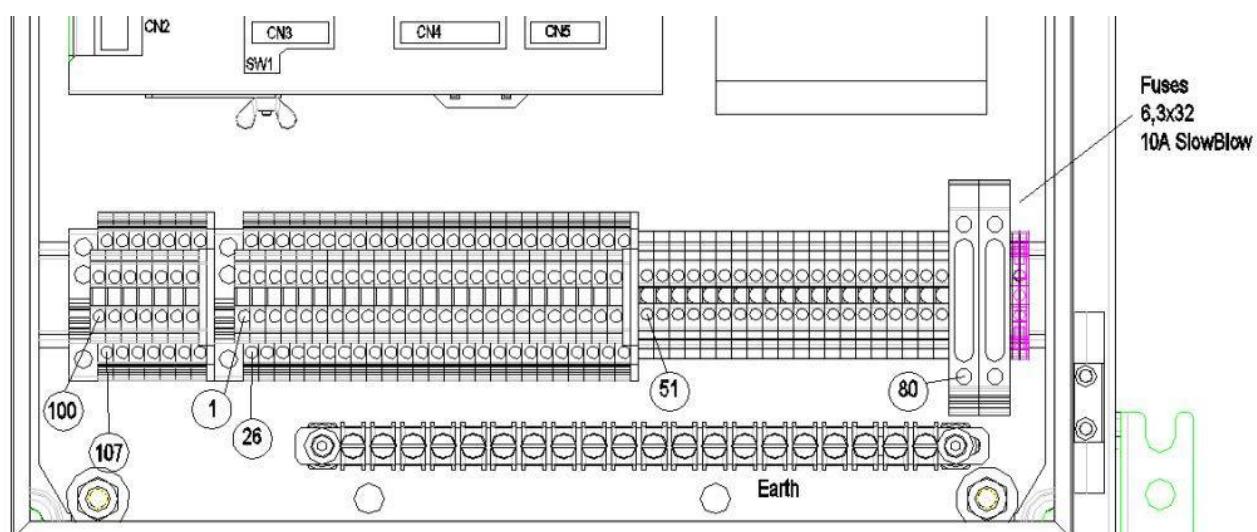
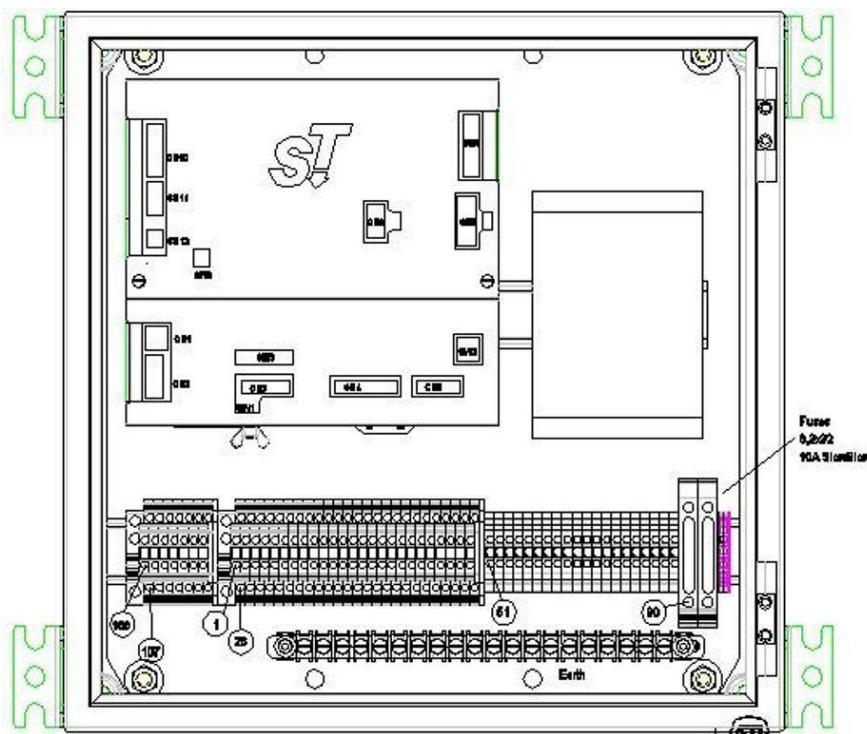
Electrical connections:

Application example :





Terminal Board : wiring specification and electrical rating





USER MANUAL ST2



Terminal board from 1 to 50 and from 100 to 113 :

Phoenix Contact UKK3 (2770011)

Double-level terminal block with a screw connection, cross section: 0.2

mm² - 2.5 mm², AWG: 28 – 12

Rated surge voltage 6 kV

Nominal current IN 32 A

Nominal voltage UN 500 V

Type of connection Screw connection

Tightening torque, min 0.5 Nm

Tightening torque max 0.6 Nm

Terminal board from 51 to 70

Phoenix Contact UK 2,5 N (3003347)

Universal terminal block with screw connection, cross section: 0,2- 2.5

mm², AWG: 24- 12

Rated surge voltage 8 kV

Nominal current IN 24 A

Nominal voltage UN 800 V

Type of connection Screw connection

Tightening torque, min 0.6 Nm

Tightening torque max 0.8 Nm

Terminal board from 80 to 81

Phoenix contact UK 6,3-HESI (3004171)

Fuse terminal block for cartridge fuse insert, cross section: 0.5 - 16

mm², AWG: 26 - 8,

Rated surge voltage 6 kV

Fuse G / 6,3 x 32

Nominal current IN 10 A

Nominal voltage UN 500 V (As a fuse terminal block)

Type of connection Screw connection

Tightening torque, min 1.2 Nm

Tightening torque max 1.5 Nm



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Terminal Board : pinout

Terminal board from 1 to 50

4-20ma Probe 2
4-20ma Probe 1

START/STOP Probe 2

START/STOP Probe 1

Pressure Sensors

Position Demand 'B'
Position demand 'A' (with HART)
4-20ma OUT 2
4-20ma OUT 1

Digital Outputs

Digital Inputs (TRIP)

26	4-20ma signal	1	4-20ma signal
27	nSTART/STOP	2	GND
28	nINIT	3	START/STOP
29	+24 Probe	4	INIT
30	nSTART/STOP	5	GND
31	nINIT	6	START/STOP
32	+24 Probe	7	INIT
33	+5SENS_PRESS	8	GNDSENS_PRESS
34	ANALOG_IN6	9	+24SENS_PRESS
35	ANALOG_IN4	10	ANALOG_IN5
36	ANALOG_IN2	11	ANALOG_IN3
37	RX4-20_2-	12	ANALOG_IN1
38	RX4-20_1- (HART)	13	RX4-20_2+
39	TX4-20_2-	14	RX4-20_1+ (HART)
40	TX4-20_1-	15	TX4-20_2+
41	RELE' 30	16	TX4-20_1+
42	RELE' 20	17	RELE' 3C
43	RELE' 10	18	RELE' 2C
44	TRIP1 COM	19	RELE' 1C
45	TRIP6+	20	TRIP6-
46	TRIP5+	21	TRIP5-
47	TRIP4+	22	TRIP4-
48	TRIP3+	23	TRIP3-
49	TRIP2+	24	TRIP2-
50	TRIP1+	25	TRIP1-



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Terminal board from 51 to 70

ON/OFF valves

51	SOV1+
52	SOV1-
53	SOV2+
54	SOV2-
55	SOV3+
56	SOV3-
57	SOV4+
58	SOV4-
59	SOV5+
60	SOV5-
61	SOV6+
62	SOV6-
63	PROP_VALVE_A_1+
64	PROP_VALVE_A_1-
65	PROP_VALVE_A_2+
66	PROP_VALVE_A_2-
67	PROP_VALVE_A_3+
68	PROP_VALVE_A_3-
69	PROP_VALVE_A_4+
70	PROP_VALVE_A_4-

Proportional Valves

Terminal board from 80 to 82

Power Supply

80	
81	
82	EARTH

AC Power supply :

80 = Line

81 = Neutral

DC Power supply :

80 = Positive input

81 = Negative input



USER MANUAL

ST2



Terminal board from 100 to 113

COMMUNICATION OPTIONAL

107	exp 485 'A'	100	exp 485 'B'
108	exp 485 'Y'	101	exp 485 'Z'
109		102	exp 485 GND
110	CAN 'L'	103	CAN 'H'
111		104	CAN GND
112	EXT DISP 'B'	105	EXT DISP 'A'
113	EXT DISP +24	106	EXT DISP GND



Position Feedback Probe

You can use two different type of position feedback probe :

Micropulse transducers or 4-20mA.

FeedBack PROBE

CH1

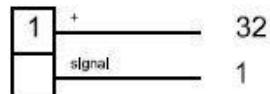
Balluff Probe	Terminal board
BTL5-P1	
1 INIT	7
2 START/STOP	6
3 nINIT	31
4	
5 nSTART/STOP	30
6 GND	5
7 +24V	32

CH2

Balluff Probe	Terminal board
BTL5-P1	
1 INIT	4
2 START/STOP	3
3 nINIT	28
4	
5 nSTART/STOP	27
6 GND	2
7 +24V	29

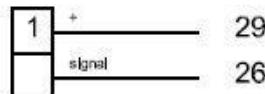
or

4-20mA Position Transmitter



or

4-20mA Position Transmitter



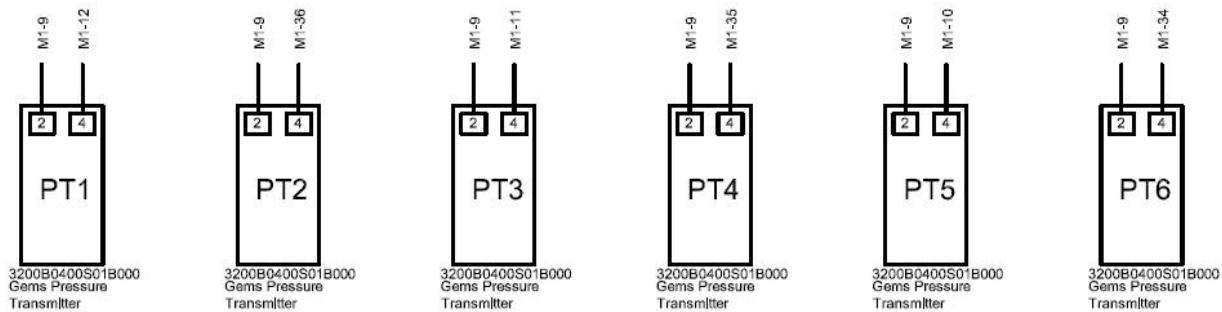
- BTL5-P1 Balluff Micropulse transducer (or equivalent)
 - o The probe is powered at 24V=.
 - o Shield of the cable can be connected in the ST2 earth connection bar. Depending on the quality of the earth connection in the field could be necessary remove the earth connection of the probe or connect it at the gnd terminal board.
- 4-20mA signal transmitter (for example STI2030)
 - The position transmitter is energized with a 24V= power supply.
 - The measurement resistor inside ST2 is equal to 120 ohms.



Analog Input (pressure sensors)

6 input for 4-20mA (or 0-5V) are available.

PRESSURE TRANSMITTER



SW3 dip switch select if the input is for 0-5V (dip in OFF position) or 4-20mA (dip in ON position).
SW3_1 is for Analog IN1, SW3_2 is for Analog IN2 and so on.

4-20mA input (preferred solution) :

Terminal board 9 : +24V= for sensor excitation

Terminal pin 12, 36, 11, 35, 10, 34 : input signal from the sensor

Burden resistor : 227 ohms

Analog Input 0-5V :

Terminal board 33 : 5V to energize the sensors (max 100mA)

Terminal board 8 : GND

Terminal pin 12, 36, 11, 35, 10, 34 : input signal from the sensor

Resolution : 12 bits

Sampling rate : 1KHz with moving average filter.

Isolation : Analog input are not isolated and designed for local use. Take care of electrical noise effect.



USER MANUAL

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4-20mA IN : Request position

CH1 : Terminal board 14 (+) and 38 (-) . With HART communication channel

CH2 : Terminal board 13 (+) and 37 (-)

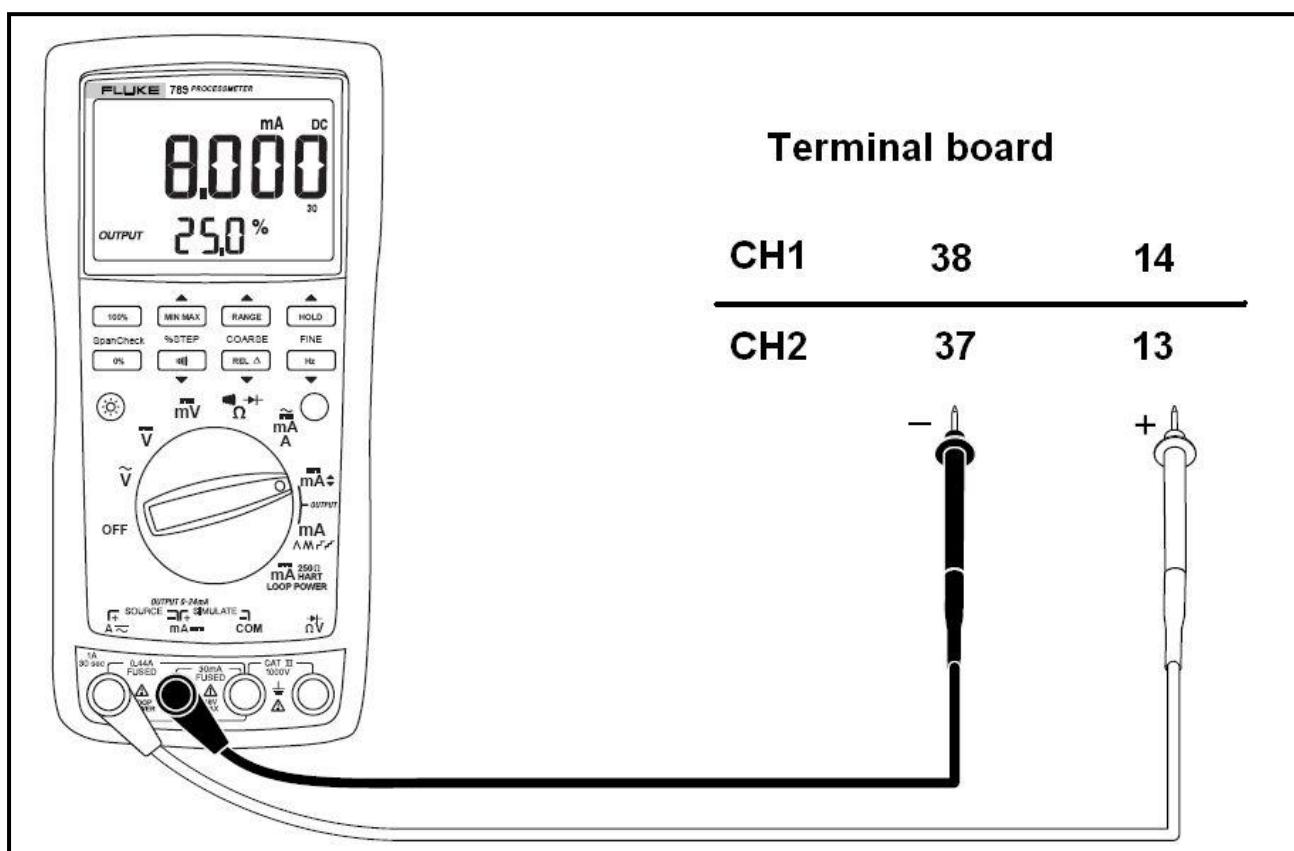
Burden resistor : 474 ohms

Resolution : 16 bits

Sampling Rate : 1KHz with filter

Hardware LowPass filter present.

Isolation : the two channels are isolated respect other electronic (microprocessor) and themselves





USER MANUAL

ST2



4-20mA OUT

Two isolated independent channels are available.

The function is configurable.

The output is energized from the loop.

CH1 : Terminal board 16 (+) and 40 (-) . CH2 : Terminal board 15 (+) and 39 (-)

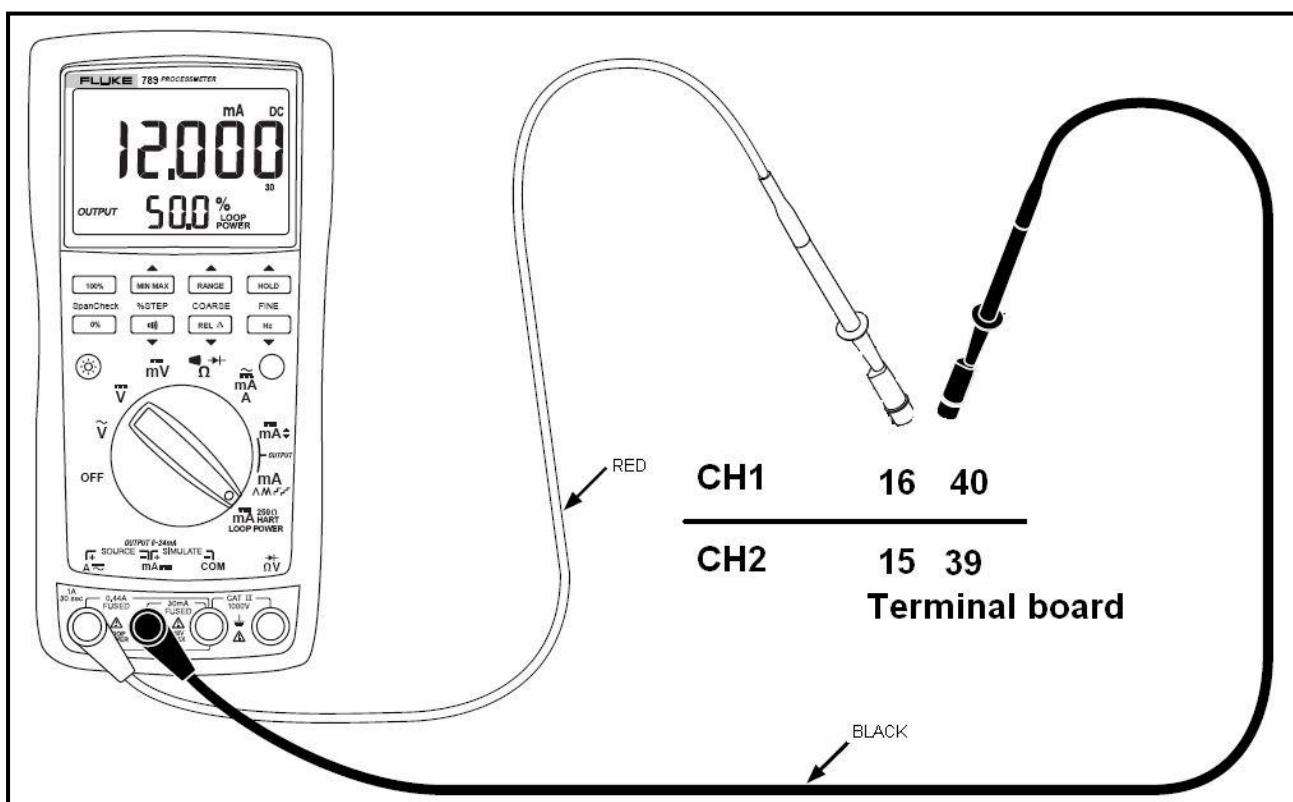
Output current (nominal) 4-20ma

Burden 750 Ω max (power supply = 24Vdc)

External power supply 24V (12..30V)

External power supply
Resolution : 12 bits

Resolution : 12 bits

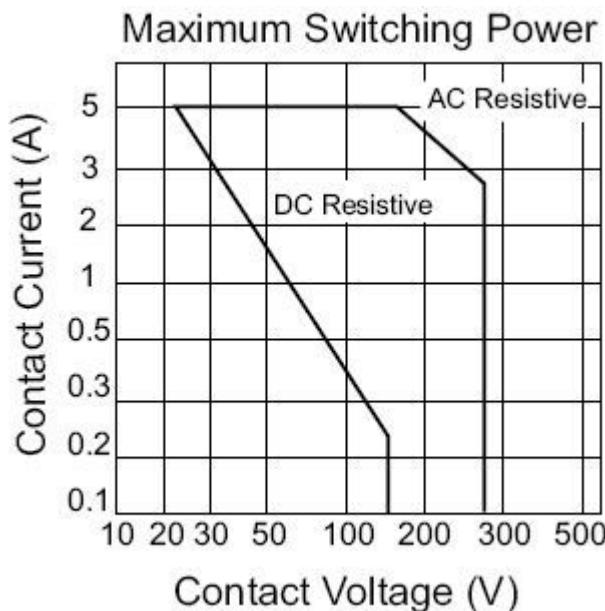




Digital output

3 independent digital output is available.

Material	Gold overlay silver alloy
Rating (resistive)	3 A 250 VAC or 3 A 30 VDC
Maximum Carrying Current	5 A
Maximum Switching Power	750 VA, 90 W
Maximum Switching Voltage	270 VAC, 150 VDC
Maximum Switching Current	5 A



For each digital output the Normally Open contact is available (i.e. DigitalOutput 1 : pin 19 and 43)
When a DigitalOutput is configured the relè is energized (and the contact become closed) when the error condition is false, and is deenergized (and the contact return to open condition) when the error condition is true.



TRIP : Digital Input

6 independent isolated TRIP digital input are available.

Each trip can be driven from a 'free contact' or from a 24V= or 24Vac signal.

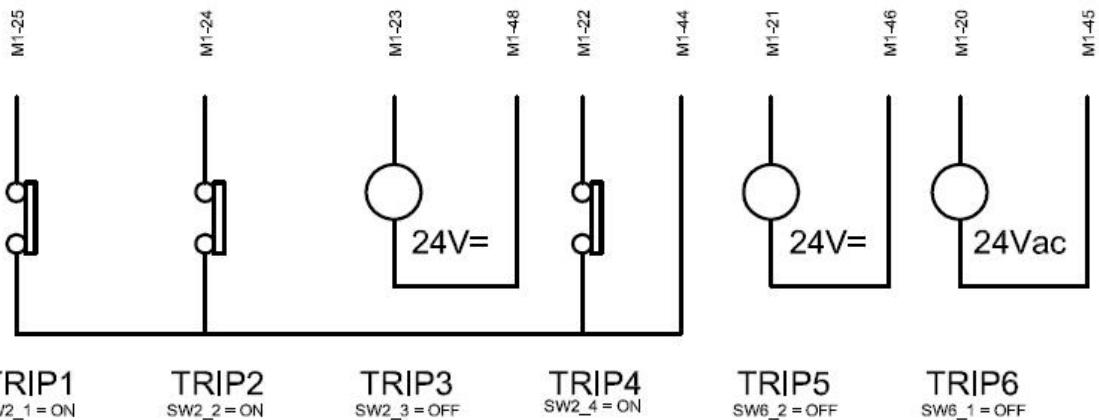
SW2 dip switch must be set in a proper way based on the type of driving signal.

Trip function is configurable in the sw.

TRIP

Example of TRIP connection

If TRIP signal is 'free contact' the proper DIPSWITCH must be ON.





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ON/OFF SOV

Up to 6 ON/OFF SOV are available.

Nominal voltage : 24V=

Nominal current : up to 2A (continuos mode, ambient = 70°C)

Power reduction : It is possible to specify for each solenoid valve a different power reduction value.

Solenoids are energized at full power, after 1 second the pwm circuit reduce the power at the specified value

Solid state driver with :

- Over temperature shutdown (with auto-restart)
- Short circuit protection (current limit)
- Full diagnostic capability
- Active clamp
- Open load detection in On and Off state

Number and power of the SOV depends on the supply unit and the number of SOV that must be energized at the same time.

Connect earth of SOV at the earth connection bar inside the ST2.



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Proportional Valve

ST2_Channel 1 : Proportional Valve A1 and A2

ST2_Channel 2 : Proportional Valve A3 and A4

Voltage output : 24V (pwm circuit allow the use of 12V solenoid)

Current output : hardware limit at 2,7A

Tested with ATOS 12V , ATOS 18V, Wandfluh 24V, Bosch

Selection of the type of proportional valve, minimum and maximum current is made by sw.



Power supply

Different solutions are available.

AC universal input (standard solution) :

The power supply module is fitted inside the controller enclosure.

Power supply module is a PhoenixContact QUINT-PS/1AC/24DC/20 able to supply 24V= with a current up to 20A.

Input range :

Nominal 100 V AC ... 240 V AC
AC range 85 V AC ... 264 V AC
DC range 90 V DC ... 350 V DC



DC 24V= input :

The power supply module is fitted inside the controller enclosure.

Power supply module is a PhoenixContact QUINT-PS-24DC/24DC/10

Check that the total power required (depending from the number of solenoid and from the schematic) is less than 240W

DC 24V= input without isolation :

No power supply module is fitted inside the enclosure. The power supply is provided from the customer. Care must be taken in the selection of cable size and length (possible problems : voltage drop, heating, noise).

We suggest to use a dedicated 24V= for each SmartTrak.

Options

(must be fitted in an external enclosure) :

Phoenix contact 2938963 Redundancy Module QUINT-DIODE/40

Phoenix contact 2866239 Uninterruptible Power Supply Unitfor Universal Use QUINT-DC-UPS/24DC/20

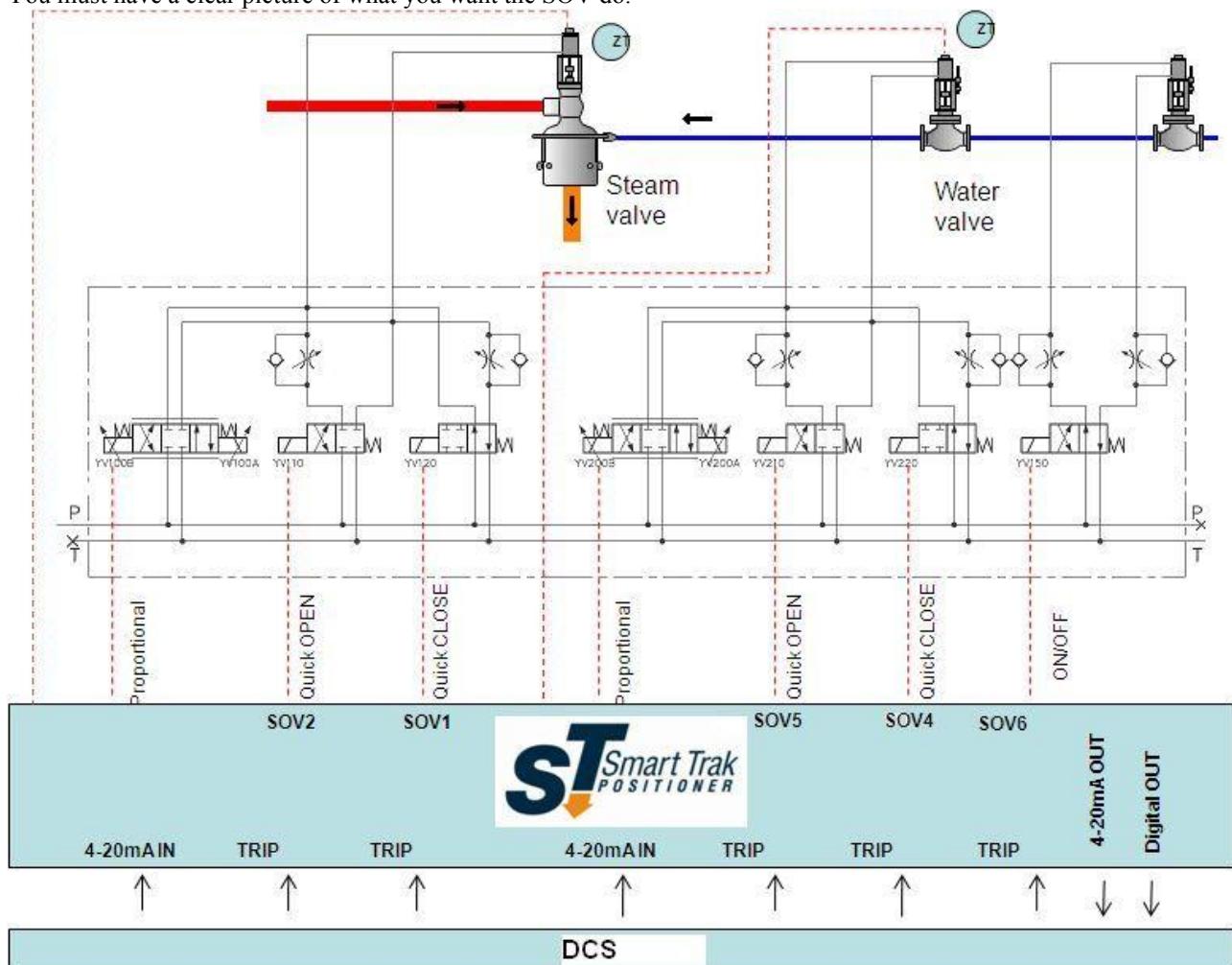
Phoenix contact 2866213 QUINT-BUFFER/24DC/20



How To (advanced user configuration guide)

Configure SOV and TRIP

You must have a clear picture of what you want the SOV do.



Referring to the standard schematic showed you have :

- SOV1 Related to channel 1 , function Quick Close
- SOV2 Related to channel 1 , function Quick Open
- SOV3 Not used
- SOV4 Related to channel 2 , function Quick Close
- SOV5 Related to channel 2 , function Quick Open
- SOV6 Direct driven from TRIP for ON/OFF water valve

- TRIP1 Quick Close command input for channel 1
- TRIP2 Quick Open command input for channel 1
- TRIP4 Quick Close command input for channel 2
- TRIP5 Quick open command input for channel 2
- TRIP6 ON/OFF water valve command



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For each TRIP signal you must know :

- The type of the TRIP signal (24Vac, 24Vdc, Free contact)
- The activation status of the TRIP (Energized, NotEnergized)

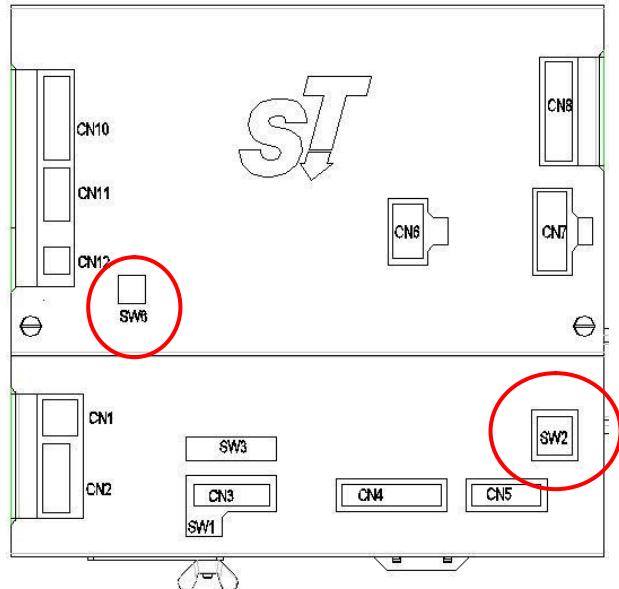
In our example we can consider the most standard configuration :

Trip Signal type = Free Contact

Activation Status = Not Energized

Setting the the Trip signal Type :

Set the SW2 and SW6 DIP-SWITCH all in the ON position like described in the 'TRIP : Digital Input' paragraph (If you have some Trip signal powered at 24Vdc or 24Vac you must turn the specific dip-switch in the off position).



Setting the Activation Status :

For TRIP1,2,4,5 select 'NotEnergized' in the RemoteControl panel.

Select the proper SafetyShutdown mode for each trip :

TRIP1=SSD1/OFF , 'NotEnergized' =SafetyShutdown1CH1 when NOTEnergized

TRIP2=SSD2/OFF , 'NotEnergized' = SafetyShutdown2CH1 when NOTEnergized

TRIP3=OFF/OFF It is not used

TRIP4=OFF/SSD4 , 'NotEnergized' = SafetyShutdown4CH2 when NOTEnergized

TRIP5=OFF/SSD5 , 'NotEnergized' = SafetyShutdown5CH2 when NOTEnergized

TRIP6=OFF/OFF , Energized Must Be configured for DirectDrive in the SOV configuration panel

TUNING		IN/OUT	
FAIL / TRIP SETTINGS			
Mode C1/C2	Ack	On St. Err Hw	
1 MV/Off	Wait No Err	E	● ●
2 Off/Off	Auto	E	● ●
3 SSD3/SSD6	Auto	E	● ●
4 Off/Off	Auto	E	● ●
5 Off/Off	Auto	E	● ●
6 Off/Off	Auto	E	● ●

Error Mode	
Channel 1	Channel 2
<input type="radio"/> Off / Direct Drive Mode	<input checked="" type="radio"/> Off / Direct Drive Mode
<input checked="" type="radio"/> Safety Shut Down 1	<input type="radio"/> Safety Shut Down 4
<input type="radio"/> Safety Shut Down 2	<input type="radio"/> Safety Shut Down 5
<input type="radio"/> Safety Shut Down 3	<input type="radio"/> Safety Shut Down 6
<input type="radio"/> Modulation Valve	<input type="radio"/> Modulation Valve
<input type="radio"/> Freeze	<input type="radio"/> Freeze
<input type="radio"/> Ack	<input type="radio"/> Ack
<input type="radio"/> External SOV	<input type="radio"/> External SOV
<input checked="" type="checkbox"/> OK	
<input type="checkbox"/> Cancel	

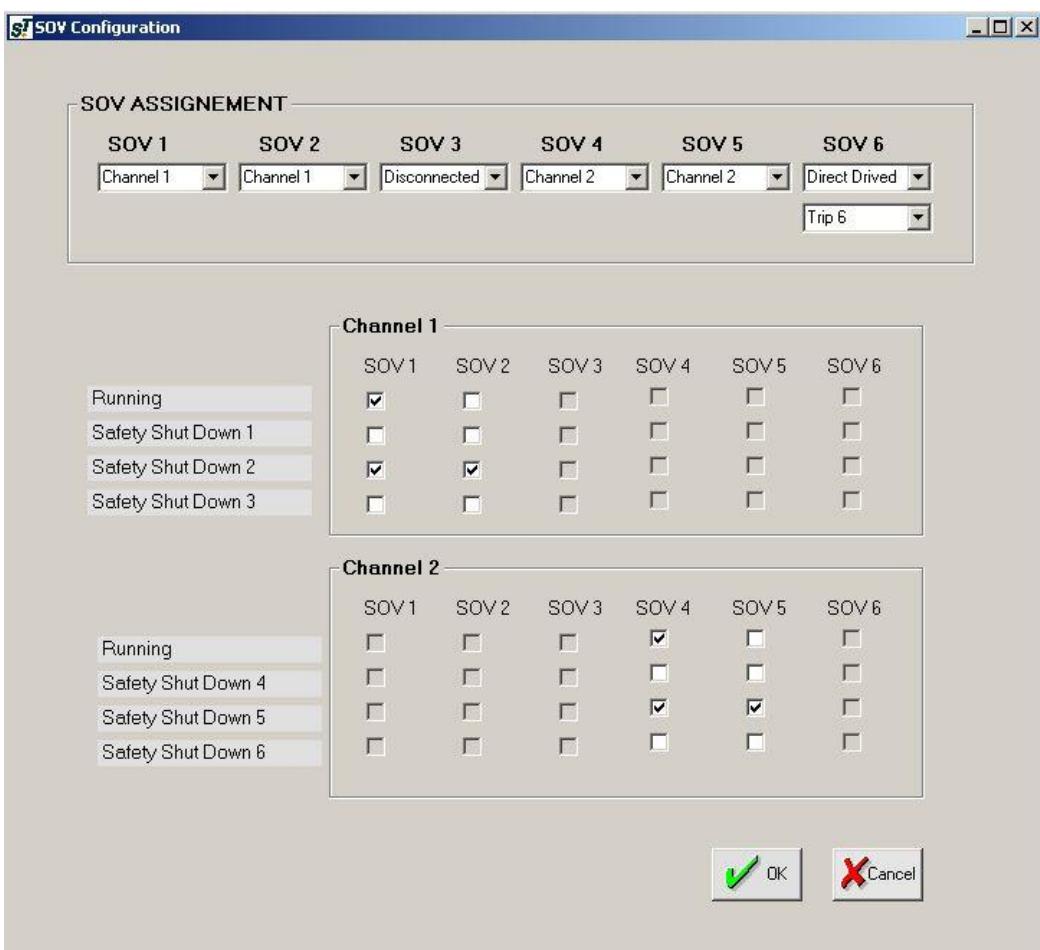


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Setting the SOV :



Set the SOV like showed in the picture.

Explanation :

Channel 1

When the SmartTrak channel 1 is in running (normal operation mode when the system is calibrated), SOV1 is energized and SOV2 is deenergized. The two ON/OFF valves are in the 'close' position, so the only valve that can control the actuator is the proportional one.

If TRIP1 is activated SOV1 is deenergized (and also SOV2) : the quick close on/off SOV drive the actuator in the CLOSE position.

If TRIP2 is activated SOV1 is energized ('close') and SOV2 is energized ('open') : the quick open on/off SOV drive the actuator in the OPEN position.

Channel 2

Same of channel 1 but with SOV4, SOV5, TRIP1, TRIP2

SOV6 : This SOV is directly driven from TRIP6. When TRIP6 is activated ('Energized') it turns on the SOV6 that open the ON/OFF valve



Configure Power reduction and test the SOV

To reduce the power consumption of the solenoids, power reduction can be configured. With that on the one hand the power dissipation of the power supply and the solenoids can be reduced, on the other hand the life time is going to be increased. The power reduction is by means of pulse-width-modulation.

With longer lines between the SmartTrak and the solenoids, pay attention that the control voltage on the solenoid through the voltage drop on the lines must not under 17 V.

When the solenoid is turned on, full power is applied for 1 second, after this time the power is reduced to the value specified (in %) in the specific configuration field.

Default value is 100% that means that power reduction is not applied.

If you specify a value of 75% it means that after 1 second the pwm circuit works at 75% with an equivalent voltage of $24V \times 75\% = 18V$

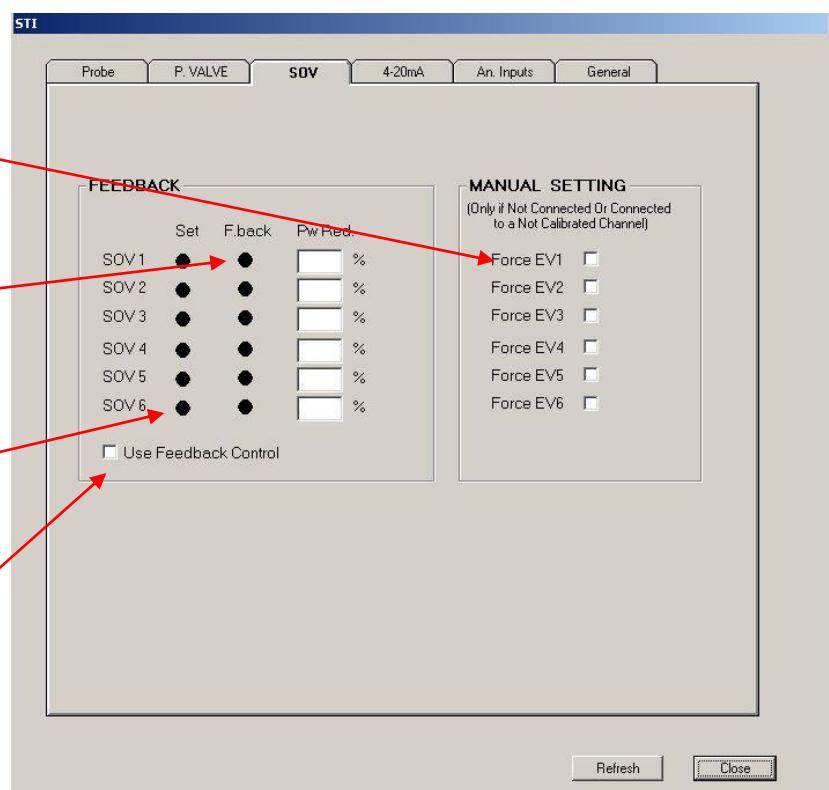
Test the SOV :

Manual Setting allow to Turn ON and OFF the SOV for diagnostic purpose (this feature is available only when the related channel is not calibrated)

The *Feedback led* indicates if the SOV is connected and works properly (the electronic circuit is able to recognize if the SOV is not connected or if it is in short circuit)

The *Set led* indicates if the required SOV status made by the sw.

'Use feedback control' enable error management of the SOV.





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Configure the Proportional Valve

Select the type of proportional valve

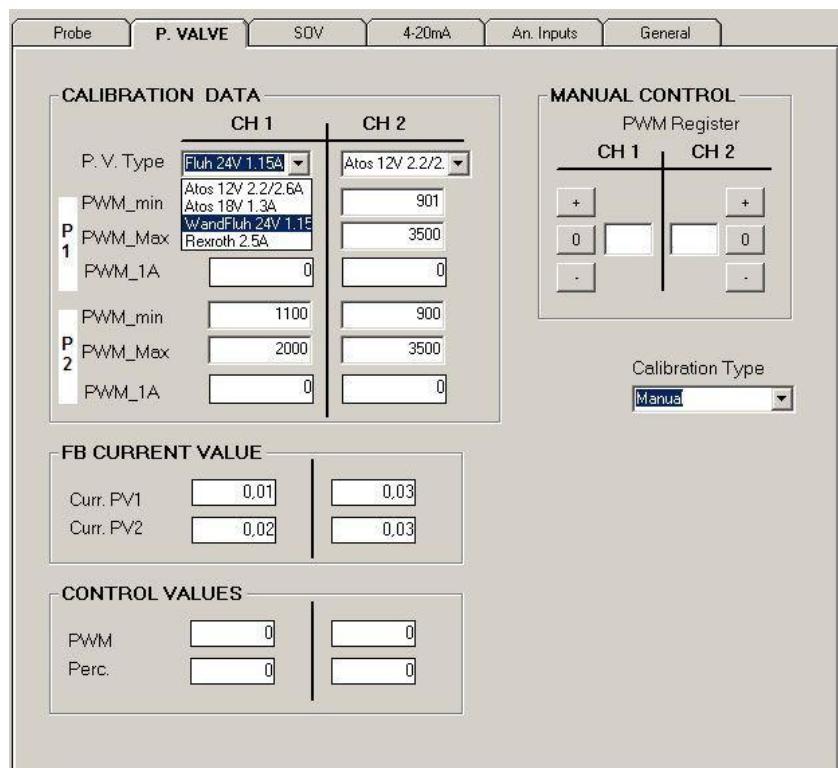
You can select from different types of proportional valves.

Each proportional valve has a specific minimum and maximum current.

When you select a specific proportional valve, default values for this valve are loaded.

During the calibration the positioner use these values for reference and find proper configuration for :

- PwmMin : minimum driver power able to move slowly the actuator
- PwmMax : default value if 'Calibration Type = manual' or pwm value able to drive the theoretical max current



FB CURRENT VALUE : Show the current applied at the proportional valve

MANUAL CONTROL :

Allow to drive manually a proportional valve for diagnostic purpose (only when the channel is not calibrated)

Tips & Tricks:

If you have a very little actuator but you have a big size proportional valve you can modify manually the PWMmax parameter in order to increase the performance of the system.

Reducing the PWMmax value you can use big Kp :

- Kp is bigger : the system is quick and able to reduce the residual error (reduce the deadband)
- PWMmax is lower : the proportional valve can't be open at full flow rate (even if you have a big kp you can reduce overshoot and instability)



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TROUBLE SHOOTING

Problem description	Cause	Solution
1. The controller doesn't switch on	1.1 The power is not connected 1.2 the power supply voltage is out of the admissible range (+/-10%) 1.3 the fuses are blown 1.4 some wiring is not properly done either inside the controller 1.5 there is a short circuit on some of the devices connected to the controller	1.1 Connect the power 1.2 check the power supply voltage value with a multimeter 1.3 replace the fuses 1.4 check the wiring using the electrical diagram 1.5 disconnect all the terminal boards connected to these device and check whether the controller switches on.
2. Probe error	2.1 some wiring is not properly done 2.2 the software selection in STI menu of the used probe is not correct 2.3 the probe has been calibrated with a shorter stroke process valve 2.4 the probe is damaged	2.1 check the wiring 2.2 check that the software setting corresponds to the used probe 2.3 erase the previous calibration and perform a new calibration 2.4 replace the probe
3. Proportional valve is not working properly	3.1 the proportional valves connectors are not properly plugged 3.2 the wiring is not properly done	3.1 check the connector plug 3.2 check the wiring
4. A change in the valve position set point doesn't affect the actuator's position	4.1 the oil pressure value is too low 4.2 the proportional valve is sticking 4.3 the parameters configuration is not correct 4.4 actuator and/or jammed valve 4.5 signal wires are not properly connected 4.6 circuit boards are defective 4.7 calibration and tuning have not been carried out 4.8 device is in "manual" or "out of service" mode 4.9 device is in fail safe status	4.1 check the oil pressure value 4.2 check that the proportional valve can slide smoothly 4.3 check gain and dead band values 4.3 check that the actuator can move in a continuous way and not in steps 4.5 check signal wires 4.6 replace circuit boards 4.7 perform a calibration and make the proper tuning 4.8 set the system in "in service" mode 4.9 check whether the solenoid valve making the fail safe mode is energized
5. Overshooting or positioning too slow	5.1 incorrect tuning in terms of dead band and gain 5.2 the proportional valve is sticking 5.3 too small oil tubing or dirty oil filter 5.4 leakages in oil tubing and manifold connections 5.5 process valve is sticking	5.1 change the dead band and gain values 5.2 check that the proportional valve can slide smoothly 5.3 check oil tubing size with the factory and inspect oil filter 5.4 check leakages in oil tubing and manifold connections 5.5 check process valve
6. Low signal fail limit	6. Low signal fail limit	6.1 check that the signal wires are properly connected to the terminal board 6.2 check with a multimeter the value of the signal
7. Position excess error	7. Position excess error	7. see point 4. of this table



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8. Position excess warning	8. Position excess warning	8. see point 4. of this table
9. Hard limits error	9. Hard limits error	9.1 check the probe is working properly 9.2 check that the oil supply value is not too low
10. Error on solenoid valve SOVx	10. Error on solenoid valve SOVx	10.1 check that the solenoid valve's coil is not burnt 10.2 check the wiring between the solenoid valve and the controller
11. Calibration erased	11. Calibration erased	11. This is a warning message used to inform that a calibration parameters reset has been performed by the operator
12. Waiting ACK		12. in order to go back to normal operation an "ack" command must be provided
13. External SOV warning	13. this is a warning message showing that a solenoid valve not energized by the controller has taken the system into the fail safe position	



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ST2Mono : single channel version

Based on the same electronic, a single channel version is available.

The electronic is partially mounted, the terminal board is different, the sw is the same and is able to recognize if the electronic is suitable for a double channel or for a single one.

Differences :

	<i>ST2</i>	<i>ST2Mono</i>
TRIP digital Inputs	6	4
SOV	6	3
Proportional valve driver	2	1
4-20mA Analog Output	2	2
Digital Output	3	3
Start/Stop Feedback Probe	2	1
4-20mA Feedback Probe	2	1
Analog inputs	6	3
4-20mA inputs (setpoint)	2	1
Hart	✓	✓
RemoteControl	✓	✓
SD Card	✓	✓

ST2Mono Power supply :

When the power supply selected is the 24Vdc the power supply adapter is the same for the ST2 and the ST2Mono (see chapter 'Power Supply' of this IOM).

When the power supply selected is 'AC Universal Input' a specific unit is used for the single channel version (Phoenix QUINT-PS/1AC/24DC/10) able to delivery up to 10A.



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ST2Mono : terminal board

4-20ma Probe 1

1	4-20ma signal
2	GND
3	nSTART/STOP
4	START/STOP
5	nINIT
6	INIT
7	+24 Probe

START/STOP Probe 1

8	RX4-20_1+ (HART)
9	RX4-20_1- (HART)

4-20ma OUT 1

10	TX4-20_1+
11	TX4-20_1-

4-20ma OUT 2

12	TX4-20_2+
13	TX4-20_2-

Pressure Sensors

14	GND
15	+5SENS_PRESS
16	+24SENS_PRESS
17	ANALOG_IN1
18	ANALOG_IN2
19	ANALOG_IN3

Digital Inputs (TRIP)

20	TRIP1 COM
21	TRIP1+
22	TRIP1-
23	TRIP2 COM
24	TRIP2+
25	TRIP2-
26	TRIP3 COM
27	TRIP3+
28	TRIP3-
29	TRIP4 COM
30	TRIP4+
31	TRIP4-

Digital Outputs

32	RELE' 1C
33	RELE' 1O
34	RELE' 2C
35	RELE' 2O
36	RELE' 3C
37	RELE' 3O



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ON/OFF valves

38	SOV1+
39	SOV1-
40	SOV2+
41	SOV2-
42	SOV3+
43	SOV3-
44	PROP_VALVE_A+
45	PROP_VALVE_A-
46	PROP_VALVE_B+
47	PROP_VALVE_B-

Proportional Valves

Power Supply

48	
49	
50	EARTH